

# Digital Shearlet Transforms

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## Abstract

Over the past years, various representation systems which sparsely approximate functions governed by anisotropic features such as edges in images have been proposed. We exemplarily mention the systems of contourlets, curvelets, and shearlets. Alongside the theoretical development of these systems, algorithmic realizations of the associated transforms were provided. However, one of the most common shortcomings of these frameworks is the lack of providing a unified treatment of the continuum and digital world, i.e., allowing a digital theory to be a natural digitization of the continuum theory. In fact, shearlet systems are the only systems so far which satisfy this property, yet still deliver optimally sparse approximations of cartoon-like images. In this chapter, we provide an introduction to digital shearlet theory with a particular focus on a unified treatment of the continuum and digital realm. In our survey we will present the implementations of two shearlet transforms, one based on band-limited shearlets and the other based on compactly supported shearlets. We will moreover discuss various quantitative measures, which allow an objective comparison with other directional transforms and an objective tuning of parameters. The codes for both presented transforms as well as the framework for quantifying performance are provided in the Matlab toolbox `ShearLab`.

## 1 Introduction

One key property of wavelets, which enabled their success as a universal methodology for signal processing, is the unified treatment of the continuum and digital world. In fact, the wavelet transform can be implemented by a natural digitization of the continuum theory, thus providing a theoretical foundation for the digital transform. Lately, it was observed that wavelets are however suboptimal when sparse approximations of 2D functions are sought. The reason is that these functions are typically governed by anisotropic features such as edges in images or evolving shock fronts in solutions of transport equations. However, Besov models – which wavelets optimally encode – are clearly deficient to capture these features. Within the model of cartoon-like images, introduced by Donoho in [13] in 1999, the suboptimal behavior of wavelets for such 2D functions was made mathematically precise; see also Chapter [4].

Among the various directional representation systems which have since then been proposed such as contourlets [12], curvelets [9], and shearlets, the shearlet system is in fact the only one which delivers optimally sparse approximations of cartoon-like images and still also allows for a unified treatment of the continuum and digital world. One main reason in comparison to the other two mentioned systems is the fact that shearlets are affine systems, thereby enabling an extensive theoretical framework, but parameterize directions by slope (in contrast to angles) which greatly supports treating the digital setting. As a thought experiment just note that a shear matrix leaves the digital grid  $\mathbb{Z}^2$  invariant, which is in general not true for rotation.

This raises the following questions, which we will answer in this chapter:

(P1) What are the main desiderata for a digital shearlet theory?

- (P2) Which approaches do exist to derive a natural digitization of the continuum shearlet theory?
- (P3) How can we measure the accuracy to which the desiderata from (P1) are matched?
- (P4) Can we even introduce a framework within which different directional transforms can be objectively compared?

Before delving into a detailed discussion, let us first contemplate about these questions on a more intuitive level.

## 1.1 A Unified Framework for the Continuum and Digital World

Several desiderata come to one's mind, which guarantee a unified framework for both the continuum and digital world, and provide an answer to (P1). The following are the choices of desiderata which were considered in [20, 14]:

- *Parseval Frame Property*. The transform shall ideally have the tight frame property, which enables taking the adjoint as inverse transform. This property can be broken into the following two parts, which most, but not all, transforms admit:
  - ◊ *Algebraic Exactness*. The transform should be based on a theory for digital data in the sense that the analyzing functions should be an exact digitization of the continuum domain analyzing elements.
  - ◊ *Isometry of Pseudo-Polar Fourier Transform*. If the image is first mapped into a different domain – here the pseudo-polar domain –, then this map should be an isometry.
- *Space-Frequency-Localization*. The analyzing elements of the associated transform should ideally be highly localized in space and frequency – to the extent to which uncertainty principles allow this.
- *Shear Invariance*. Shearing naturally occurs in digital imaging, and it can – in contrast to rotation – be precisely realized in the digital domain. Thus the transform should be shear invariant, i.e., a shearing of the input image should be mirrored in a simple shift of the transform coefficients.
- *Speed*. The transform should admit an algorithm of order  $O(N^2 \log N)$  flops, where  $N^2$  is the number of digital points of the input image.
- *Geometric Exactness*. The transform should preserve geometric properties parallel to those of the continuum theory, for example, edges should be mapped to edges in transform domain.
- *Stability*. The transform should be resilient against impacts such as (hard) thresholding.

## 1.2 Band-Limited Versus Compactly Supported Shearlet Transforms

In general, two different types of shearlet systems are utilized today: Band-limited shearlet systems and compactly supported shearlet systems (see also Chapters [1] and [4]). Regarding those from an algorithmic viewpoint, both have their particular advantages and disadvantages:

Algorithmic realizations of the *band-limited shearlet transform* have on the one hand typically a higher computational complexity due to the fact that the windowing takes place in frequency domain. However, on the other hand, they do allow a high localization in frequency domain which is important, for instance, for handling seismic data. Even more, band-limited shearlets do admit a precise digitization of the continuum theory.

In contrast to this, algorithmic realizations of the *compactly supported shearlet transform* are much faster and have the advantage of achieving a high accuracy in spatial domain. But for

a precise digitization one has to lower one's sights slightly. A more comprehensive answer to (P2) will be provided in the sequel of this chapter, where we will present the digital transform based on band-limited shearlets introduced in [20] and the digital transform based on compactly supported shearlets from [22].

### 1.3 Related Work

Since the introduction of directional representation systems by many pioneer researchers ([8, 9, 10, 11, 12]), various numerical implementations of their directional representation systems have been proposed. Let us next briefly survey the main features of the two closest to shearlets, which are the contourlet and curvelet algorithms.

- *Curvelets* [7]. The discrete curvelet transform is implemented in the software package *CurveLab*, which comprises two different approaches. One is based on unequidistant FFTs, which are used to interpolate the function in the frequency domain on different tiles with respect to different orientations of curvelets. The other is based on frequency wrapping, which wraps each subband indexed by scale and angle into a fixed rectangle around the origin. Both approaches can be realized efficiently in  $O(N^2 \log N)$  flops with  $N$  being the image size. The disadvantage of this approach is the lack of an associated continuum domain theory.
- *Contourlets* [12]. The implementation of contourlets is based on a directional filter bank, which produces a directional frequency partitioning similar to the one generated by curvelets. The main advantage of this approach is that it allows a tree-structured filter bank implementation, in which aliasing due to subsampling is allowed to exist. Consequently, one can achieve great efficiency in terms of redundancy and good spatial localization. A drawback of this approach is that various artifacts are introduced and that an associated continuum domain theory is missing.

Summarizing, all the above implementations of directional representation systems have their own advantages and disadvantages; one of the most common shortcomings is the lack of providing a unified treatment of the continuum and digital world.

Besides the shearlet implementations we will present in this chapter, we would like to refer to Chapter [2] for a discussion of the algorithm in [16] based on the Laplacian pyramid scheme and directional filtering. It should be though noted that this implementation is not focussed on a natural digitization of the continuum theory, which is a crucial aspect of the work presented in the sequel. We further would like to draw the reader's attention to Chapter [3] which is based on [21] aiming at introducing a shearlet MRA from a subdivision perspective. Finally, we should mention that a different approach to a shearlet MRA was recently undertaken in [17].

### 1.4 Framework for Quantifying Performance

A major problem with many computation-based results in applied mathematics is the non-availability of an accompanying code, and the lack of a fair and objective comparison with other approaches. The first problem can be overcome by following the philosophy of 'reproducible research' [15] and making the code publicly available with sufficient documentation. In this spirit, the shearlet transforms presented in this chapter are all downloadable from <http://www.shearlab.org>. One approach to overcome the second obstacle is the provision of a carefully selected set of prescribed performance measures aiming to prohibit a biased comparison on isolated tasks such as denoising and compression of specific standard images like 'Lena', 'Barbara', etc. It seems far better from an intellectual viewpoint to carefully decompose performance according to a more insightful array of tests, each one motivated by a particular well-understood property we are trying to obtain. In this chapter we will present

such a framework for quantifying performance specifically of implementations of directional transforms, which was originally introduced in [20, 14]. We would like to emphasize that such a framework does not only provide the possibility of a fair and thorough comparison, but also enables the tuning of the parameters of an algorithm in a rational way, thereby providing an answer to both (P3) and (P4).

## 1.5 ShearLab

Following the philosophy of the previously detailed thoughts, `ShearLab`<sup>1</sup> was introduced by Donoho, Shahram, and the authors. This software package contains

- An algorithm based on band-limited shearlets introduced in [20].
- An algorithm based on compactly supported separable shearlets introduced in [22].
- An algorithm based on compactly supported nonseparable shearlets introduced in [23].
- A comprehensive framework for quantifying performance of directional representations in general.

This chapter is also devoted to provide an introduction to and discuss the mathematical foundation of these components.

## 1.6 Outline

In Section 2, we introduce and analyze the fast digital shearlet transform FDST, which is based on band-limited shearlets. Section 3 is then devoted to the presentation and discussion of the digital separable shearlet transform DSST and the digital non-separable shearlet transform DNST. The framework of performance measures for parabolic scaling based transforms is provided in Section 4. In the same section, we further discuss these measures for the special cases of the three previously introduced transforms.

## 2 Digital Shearlet Transform using Band-Limited Shearlets

The first algorithmic realization of a digital shearlet transform we will present, coined *Fast Digital Shearlet Transform (FDST)*, is based on band-limited shearlets. Let us start by defining the class of shearlet systems we are interested in. Referring to Chapter [1], we will consider the cone-adapted discrete shearlet system  $SH(\phi, \psi, \tilde{\psi}; \Delta, \Lambda, \tilde{\Lambda}) = \Phi(\phi; \Delta) \cup \Psi(\psi; \Lambda) \cup \tilde{\Psi}(\tilde{\psi}; \tilde{\Lambda})$  with  $\Delta = \mathbb{Z}^2$  and

$$\Lambda = \tilde{\Lambda} = \{(j, k, m) : j \geq 0, |k| \leq 2^j, m \in \mathbb{Z}^2\}.$$

We wish to emphasize that this choice relates to a scaling by  $4^j$  yielding an integer valued parabolic scaling matrix, which is better adapted to the digital setting than a scaling by  $2^j$ . We further let  $\psi$  be a classical shearlet ( $\tilde{\psi}$  likewise with  $\tilde{\psi}(\xi_1, \xi_2) = \psi(\xi_2, \xi_1)$ ), i.e.,

$$\hat{\psi}(\xi) = \hat{\psi}(\xi_1, \xi_2) = \hat{\psi}_1(\xi_1) \hat{\psi}_2\left(\frac{\xi_2}{\xi_1}\right), \quad (2.1)$$

where  $\psi_1 \in L^2(\mathbb{R})$  is a wavelet with  $\hat{\psi}_1 \in C^\infty(\mathbb{R})$  and  $\text{supp } \hat{\psi}_1 \subseteq [-4, -\frac{1}{4}] \cup [\frac{1}{4}, 4]$ , and  $\psi_2 \in L^2(\mathbb{R})$  a ‘bump’ function satisfying  $\hat{\psi}_2 \in C^\infty(\mathbb{R})$  and  $\text{supp } \hat{\psi}_2 \subseteq [-1, 1]$ . We remark that the chosen support deviates slightly from the choice in the introduction, which is however just a minor adaption again to prepare for the digitization. Further, recall the definition of the cones  $\mathcal{C}_{11} - \mathcal{C}_{22}$  from Chapter [1].

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<sup>1</sup>ShearLab (Version 1.1) is available from <http://www.shearlab.org>.

The digitization of the associated discrete shearlet transform will be performed in the frequency domain. Focussing, on the cone  $\mathcal{C}_{21}$ , say, the discrete shearlet transform is of the form

$$f \mapsto \langle f, \psi_\eta \rangle = \langle \hat{f}, \hat{\psi}_\eta \rangle = \left\langle \hat{f}, 2^{-j\frac{3}{2}} \hat{\psi}(S_k^T A_{4^{-j}} \cdot) e^{2\pi i \langle A_{4^{-j}} S_k m, \cdot \rangle} \right\rangle, \quad (2.2)$$

where  $\eta = (j, k, m, t)$  indexes *scale*  $j$ , *orientation*  $k$ , *position*  $m$ , and *cone*  $t$ . Considering this shearlet transform for continuum domain data (taking all cones into account) implicitly induces a trapezoidal tiling of frequency space which is evidently not cartesian. A digital grid perfectly adapted to this situation is the so-called ‘pseudo-polar grid’, which we will introduce and discuss subsequently in detail. Let us for now mention that this viewpoint enables representation of the discrete shearlet transform as a cascade of three steps:

- 1) Classical Fourier transformation and change of variables to pseudo-polar coordinates.
- 2) Weighting by a radial ‘density compensation’ factor.
- 3) Decomposition into rectangular tiles and inverse Fourier transform of each tiles.

Before discussing these steps in detail, let us give an overview of how these steps will be faithfully digitized. First, it will be shown in Subsection 2.1, that the two operations in Step 1) can be combined to the so-called pseudo-polar Fourier transform. An oversampling in radial direction of the pseudo-polar grid, on which the pseudo-polar Fourier transform is computed, will then enable the design of ‘density-compensation-style’ weights on those grid points leading to Steps 1) & 2) being an isometry. This will be discussed in Subsection 2.2. Subsection 2.3 is then concerned with the digitization of the discrete shearlets to subband windows. Notice that a digital analog of (2.2) moreover requires an additional 2D-iFFT. Thus, concluding the digitization of the discrete shearlet transform will cascade the following steps, which is the exact analogy of the continuum domain shearlet transform (2.2):

- (S1) PPFT: Pseudo-polar Fourier transform with oversampling factor in the radial direction.
- (S2) Weighting: Multiplication by ‘density-compensation-style’ weights.
- (S3) Windowing: Decomposing the pseudo-polar grid into rectangular subband windows with additional 2D-iFFT.

With a careful choice of the weights and subband windows, this transform is an isometry. Then the inverse transform can be computed by merely taking the adjoint in each step. A final discussion on the FDST will be presented in Subsection 2.4.

## 2.1 Pseudo-Polar Fourier Transform

We start by discussing Step (S1).

### 2.1.1 Pseudo-Polar Grids with Oversampling

In [5], a fast pseudo-polar Fourier transform (PPFT) which evaluates the discrete Fourier transform at points on a trapezoidal grid in frequency space, the so-called pseudo-polar grid, was already developed. However, the direct use of the PPFT is problematic, since it is – as defined in [5] – not an isometry. The main obstacle is the highly nonuniform arrangement of the points on the pseudo-polar grid. This intuitively suggests to downweight points in regions of very high density by using weights which correspond roughly to the density compensation weights underlying the continuous change of variables. This will be enabled by a sufficient radial oversampling of the pseudo-polar grid.

This new pseudo-polar grid, which we will denote in the sequel by  $\Omega_R$  to indicate the over-sampling rate  $R$ , is defined by

$$\Omega_R = \Omega_R^1 \cup \Omega_R^2, \quad (2.3)$$

where

$$\Omega_R^1 = \left\{ \left( -\frac{2n}{R}, \frac{2\ell}{N}, \frac{2n}{R} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, -\frac{RN}{2} \leq n \leq \frac{RN}{2} \right\}, \quad (2.4)$$

$$\Omega_R^2 = \left\{ \left( \frac{2n}{R}, -\frac{2\ell}{N}, \frac{2n}{R} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, -\frac{RN}{2} \leq n \leq \frac{RN}{2} \right\}. \quad (2.5)$$

This grid is illustrated in Fig. 1. We remark that the pseudo-polar grid introduced in [5] coincides with  $\Omega_R$  for the particular choice  $R = 2$ . It should be emphasized that  $\Omega_R = \Omega_R^1 \cup \Omega_R^2$  is not a disjoint partitioning, nor is the mapping  $(n, \ell) \mapsto \left( -\frac{2n}{R}, \frac{2\ell}{N}, \frac{2n}{R} \right)$  or  $\left( \frac{2n}{R}, -\frac{2\ell}{N}, \frac{2n}{R} \right)$  injective. In fact, the center

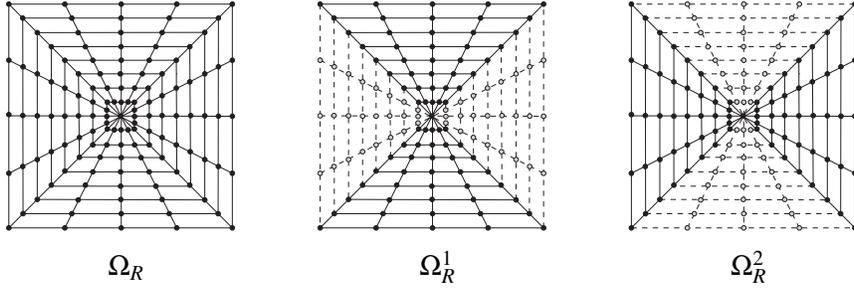


Figure 1: The pseudo-polar grid  $\Omega_R = \Omega_R^1 \cup \Omega_R^2$  for  $N = 4$  and  $R = 4$ .

appears  $N + 1$  times in  $\Omega_R^1$  as well as  $\Omega_R^2$ , and the points on the seam lines

$$\mathcal{C} = \{(0, 0)\} \quad (2.6)$$

appear in both  $\Omega_R^1$  and  $\Omega_R^2$ .

$$\begin{aligned} \mathcal{S}_R^1 &= \left\{ \left( -\frac{2n}{R}, \frac{2n}{R} \right) : -\frac{RN}{2} \leq n \leq \frac{RN}{2}, n \neq 0 \right\}, \\ \mathcal{S}_R^2 &= \left\{ \left( \frac{2n}{R}, -\frac{2n}{R} \right) : -\frac{RN}{2} \leq n \leq \frac{RN}{2}, n \neq 0 \right\}. \end{aligned}$$

appear in both  $\Omega_R^1$  and  $\Omega_R^2$ .

**Definition 2.1.** Let  $N, R$  be positive integer, and let  $\Omega_R$  be the pseudo-polar grid given by (2.3). For an  $N \times N$  image  $I := \{I(u, v) : -\frac{N}{2} \leq u, v \leq \frac{N}{2} - 1\}$ , the pseudo-polar Fourier transform (PPFT)  $\hat{I}$  of  $I$  evaluated on  $\Omega_R$  is then defined to be

$$\hat{I}(\omega_1, \omega_2) = \sum_{u, v = -N/2}^{N/2-1} I(u, v) e^{-\frac{2\pi i}{m_0}(u\omega_1 + v\omega_2)}, \quad (\omega_1, \omega_2) \in \Omega_R,$$

where  $m_0 \geq N$  is an integer.

We wish to mention that  $m_0 \geq N$  is typically set to be  $m_0 = \frac{2}{R}(RN + 1)$  for computational reasons (see also [5]), but we for now allow more generality.

### 2.1.2 Fast PPFT

It was shown in [5], that the PPFT can be realized in  $O(N^2 \log N)$  flops with  $N \times N$  being the size of the input image. We will now discuss how the extended pseudo-polar Fourier transform as defined in Definition 2.1 can be computed with similar complexity.

For this, let  $I$  be an image of size  $N \times N$ . Also,  $m_0$  is set – but not restricted – to be  $m_0 = \frac{2}{R}(RN + 1)$ ; we will elaborate on this choice at the end of this subsection. We now focus on  $\Omega_R^1$ , and mention that the PPFT on the other cone can be computed similarly. Rewriting the pseudo-polar Fourier transform from Definition 2.1, for  $(\omega_1, \omega_2) = (-\frac{2n}{R} \cdot \frac{2\ell}{N}, \frac{2n}{R}) \in \Omega_R^1$ , we obtain

$$\begin{aligned} \hat{I}(\omega_1, \omega_2) &= \sum_{u,v=-N/2}^{N/2-1} I(u,v) e^{-\frac{2\pi i}{m_0}(u\omega_1+v\omega_2)} = \sum_{u=-N/2}^{N/2-1} \sum_{v=-N/2}^{N/2-1} I(u,v) e^{-\frac{2\pi i}{m_0}(u \cdot \frac{-4n\ell}{RN} + v \cdot \frac{2n}{R})} \\ &= \sum_{u=-N/2}^{N/2-1} \left( \sum_{v=-N/2}^{N/2-1} I(u,v) e^{-\frac{2\pi i v n}{RN+1}} \right) e^{-2\pi i u \ell \cdot \frac{-2n}{(RN+1)N}}. \end{aligned} \quad (2.7)$$

This rewritten form, i.e., (2.7), suggests that the pseudo-polar Fourier transform  $\hat{I}$  of  $I$  on  $\Omega_R^1$  can be obtained by performing the 1D FFT on the extension of  $I$  along direction  $v$  and then applying a fractional Fourier transform (frFT) along direction  $u$ . To be more specific, we require the following operations:

*Fractional Fourier Transform.* For  $c \in \mathbb{C}^{N+1}$ , the (unaliased) discrete fractional Fourier transform by  $\alpha \in \mathbb{C}$  is defined to be

$$(F_{N+1}^\alpha c)(k) := \sum_{j=-N/2}^{N/2} c(j) e^{-2\pi i \cdot j \cdot k \cdot \alpha}, \quad k = -\frac{N}{2}, \dots, \frac{N}{2}.$$

It was shown in [6], that the fractional Fourier transform  $F_{N+1}^\alpha c$  can be computed using  $O(N \log N)$  operations. For the special case of  $\alpha = 1/(N+1)$ , the fractional Fourier transform becomes the (unaliased) 1D discrete Fourier Transform (1D FFT), which in the sequel will be denoted by  $F_1$ . Similarly, the 2D discrete Fourier Transform (2D FFT) will be denoted by  $F_2$ , and the inverse of the  $F_2$  by  $F_2^{-1}$  (2D iFFT).

*Padding Operator.* For  $N$  even,  $m > N$  an odd integer, and  $c \in \mathbb{C}^N$ , the padding operator  $E_{m,n}$  gives a symmetrically zero padding version of  $c$  in the sense that

$$(E_{m,n}c)(k) = \begin{cases} c(k) & k = -\frac{N}{2}, \dots, \frac{N}{2} - 1, \\ 0 & k \in \{-\frac{m}{2}, \dots, \frac{m}{2}\} \setminus \{-\frac{N}{2}, \dots, \frac{N}{2} - 1\}. \end{cases}$$

Using these operators, (2.7) can be computed by

$$\begin{aligned} \hat{I}(\omega_1, \omega_2) &= \sum_{u=-N/2}^{N/2-1} F_1 \circ E_{RN+1,N} \circ I(u,n) e^{-2\pi i u \ell \cdot \frac{-n}{(RN+1)N/2}} \\ &= \sum_{u=-N/2}^{N/2} E_{N+1,N} \circ F_1 \circ E_{RN+1,N} \circ I(u,n) e^{-2\pi i u \ell \cdot \frac{-2n}{(RN+1)N}} \\ &= (F_{N+1}^{\alpha_n} \tilde{I}(\cdot, n))(\ell), \end{aligned}$$

where  $\tilde{I} = E_{N+1,N} \circ F_1 \circ E_{RN+1,N} \circ I \in \mathbb{C}^{(RN+1) \times (N+1)}$  and  $\alpha_n = -\frac{n}{(RN+1)N/2}$ . Since the 1D FFT and 1D frFT require only  $O(N \log N)$  operations for a vector of size  $N$ , the total complexity of this algorithm for computing the pseudo-polar Fourier transform from Definition 2.1 is indeed  $O(N^2 \log N)$  for an image of size  $N \times N$ .

We would like to also remark that for a different choice of constant  $m_0$ , one can compute the pseudo-polar Fourier transform also with complexity  $O(N^2 \log N)$  for an image of size  $N \times N$ . This however requires application of the fractional Fourier transform in both directions  $u$  and  $v$  of the image, which results in a larger constant for the computational cost; see also [6].

## 2.2 Density-Compensation Weights

Next we tackle Step (S2), which is more delicate than it might seem, since the weights will not be derivable from simple density compensation arguments.

### 2.2.1 A Plancherel Theorem for the PPFT

For this, we now aim to choose weights  $w : \Omega_R \rightarrow \mathbb{R}^+$  so that the extended PPFT from Definition 2.1 becomes an isometry, i.e.,

$$\sum_{u,v=-N/2}^{N/2-1} |I(u,v)|^2 = \sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot |\hat{I}(\omega_1, \omega_2)|^2. \quad (2.8)$$

Observing the symmetry of the pseudo-polar grid, it seems natural to select weight functions  $w$  which have full axis symmetry properties, i.e., for all  $(\omega_1, \omega_2) \in \Omega_R$ , we require

$$w(\omega_1, \omega_2) = w(\omega_2, \omega_1), \quad w(\omega_1, \omega_2) = w(-\omega_1, \omega_2), \quad w(\omega_1, \omega_2) = w(\omega_1, -\omega_2). \quad (2.9)$$

Then the following ‘Plancherel theorem’ for the pseudo-polar Fourier transform on  $\Omega_R$  – similar to the one for the Fourier transform on the cartesian grid – can be proved.

**Theorem 2.1** ([20]). *Let  $N$  be even, and let  $w : \Omega_R \rightarrow \mathbb{R}^+$  be a weight function satisfying (2.9). Then (2.8) holds, if and only if, the weight function  $w$  satisfies*

$$\begin{aligned} \delta(u,v) &= w(0,0) \\ &+ 4 \cdot \sum_{\ell=0, N/2}^{RN/2} \sum_{n=1}^{RN/2} w\left(\frac{2n}{R}, \frac{2n}{R} \cdot \frac{-2\ell}{N}\right) \cdot \cos\left(2\pi u \cdot \frac{2n}{m_0 R}\right) \cdot \cos\left(2\pi v \cdot \frac{2n}{m_0 R} \cdot \frac{2\ell}{N}\right) \\ &+ 8 \cdot \sum_{\ell=1}^{N/2-1} \sum_{n=1}^{RN/2} w\left(\frac{2n}{R}, \frac{2n}{R} \cdot \frac{-2\ell}{N}\right) \cdot \cos\left(2\pi u \cdot \frac{2n}{m_0 R}\right) \cdot \cos\left(2\pi v \cdot \frac{2n}{m_0 R} \cdot \frac{2\ell}{N}\right) \end{aligned} \quad (2.10)$$

for all  $-N+1 \leq u, v \leq N-1$ .

*Proof.* We start by computing the right hand side of (2.8):

$$\begin{aligned} &\sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot |\hat{I}(\omega_1, \omega_2)|^2 \\ &= \sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot \left| \sum_{u,v=-N/2}^{N/2-1} I(u,v) e^{-\frac{2\pi i}{m_0} (u\omega_1 + v\omega_2)} \right|^2 \\ &= \sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot \left[ \sum_{u,v=-N/2}^{N/2-1} \sum_{u',v'=-N/2}^{N/2-1} I(u,v) \overline{I(u',v')} e^{-\frac{2\pi i}{m_0} ((u-u')\omega_1 + (v-v')\omega_2)} \right] \\ &= \sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot \sum_{u,v=-N/2}^{N/2-1} |I(u,v)|^2 \\ &\quad + \sum_{\substack{u,v,u',v'=-N/2 \\ (u,v) \neq (u',v')}}^{N/2-1} I(u,v) \overline{I(u',v')} \cdot \left[ \sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot e^{-\frac{2\pi i}{m_0} ((u-u')\omega_1 + (v-v')\omega_2)} \right]. \end{aligned}$$

Choosing  $I = c_{u_1, v_1} \delta(u - u_1, v - v_1) + c_{u_2, v_2} \delta(u - u_2, v - v_2)$  for all  $-N/2 \leq u_1, v_1, u_2, v_2 \leq N/2 - 1$  and for all  $c_{u_1, v_1}, c_{u_2, v_2} \in \mathbb{C}$ , we can conclude that (2.8) holds if and only if

$$\sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot e^{-\frac{2\pi i}{m_0} (u\omega_1 + v\omega_2)} = \delta(u,v), \quad -N+1 \leq u, v \leq N-1.$$

By the symmetry of the weights (2.9), this is equivalent to

$$\sum_{(\omega_1, \omega_2) \in \Omega_R} w(\omega_1, \omega_2) \cdot [\cos(\frac{2\pi}{m_0} u \omega_1) \cos(\frac{2\pi}{m_0} v \omega_2)] = \delta(u, v) \quad (2.11)$$

for all  $-N+1 \leq u, v \leq N-1$ . From this, we can deduce that (2.11) is equivalent to (2.10), which proves the theorem.  $\square$   $\square$

Notice that (2.10) is a linear system with  $RN^2/4 + RN/2 + 1$  unknowns and  $(2N-1)^2$  equations, wherefore, in general, one needs the oversampling factor  $R$  to be at least 16 to enforce solvability.

## 2.2.2 Relaxed Form of Weight Functions

The computation of the weights satisfying Theorem 2.1 by solving the full linear system of equations (2.10) is much too complex. Hence, we relax the requirement for exact isometric weighting, and represent the weights in terms of undercomplete basis functions on the pseudopolar grid.

More precisely, we first choose a set of basis functions  $w_1, \dots, w_{n_0} : \Omega_R \rightarrow \mathbb{R}^+$  such that

$$\sum_{j=1}^{n_0} w_j(\omega_1, \omega_2) \neq 0 \quad \text{for all } (\omega_1, \omega_2) \in \Omega_R.$$

We then represent weight functions  $w : \Omega_R \rightarrow \mathbb{R}^+$  by

$$w := \sum_{j=1}^{n_0} c_j w_j, \quad (2.12)$$

with  $c_1, \dots, c_{n_0}$  being nonnegative constants. This approach now enables solving (2.10) for the constants  $c_1, \dots, c_{n_0}$  using the least squares method, thereby reducing the computational complexity significantly. The ‘full’ weight function  $w$  is then given by (2.12).

We next present two different choices of weights which were derived by this relaxed approach. Notice that  $(\omega_1, \omega_2)$  and  $(n, \ell)$  will be used interchangeably.

**Choice 1.** The set of basis functions  $w_1, \dots, w_5$  is defined as follows:

*Center:*

$$w_1 = 1_{(0,0)},$$

*Boundary:*

$$w_2 = 1_{\{(\omega_1, \omega_2) : |n|=NR/2, \omega_1=\omega_2\}} \text{ and } w_3 = 1_{\{(\omega_1, \omega_2) : |n|=NR/2, \omega_1 \neq \omega_2\}},$$

*Seam lines:*

$$w_4 = |n| \cdot 1_{\{(\omega_1, \omega_2) : 1 \leq |n| < NR/2, \omega_1=\omega_2\}},$$

*Interior:*

$$w_5 = |n| \cdot 1_{\{(\omega_1, \omega_2) : 1 \leq |n| < NR/2, \omega_1 \neq \omega_2\}}.$$

**Choice 2.** The set of basis functions  $w_1, \dots, w_{N/2+2}$  is defined as follows:

*Center:*

$$w_1 = 1_{(0,0)},$$

*Radial Lines:*

$$w_{\ell+2} = 1_{\{(\omega_1, \omega_2) : 1 < |n| < NR/2, \omega_2 = \frac{\ell}{N/2} \omega_1\}}, \quad \ell = 0, 1, \dots, N/2.$$

The associated weight functions are displayed in Fig. 2. In general, suitable weight functions usually obey the pattern of linearly increasing values along the radial direction. Thus, this is a natural requirement for the basis functions.

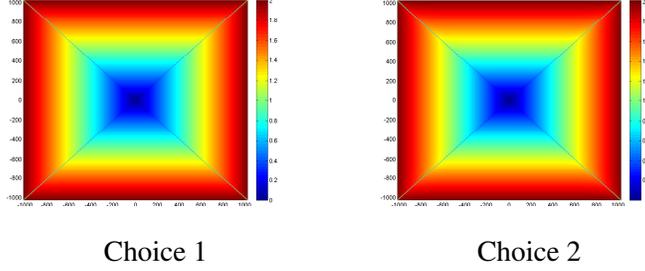


Figure 2: Weight functions on the pseudo-polar grid for  $N = 256$  and  $R = 8$ .

### 2.2.3 Computation of the Weighting

For the FDST – as also in the implementation in `ShearLab` – the coefficients in the expansion (2.12) will be computed off-line, and then hardwired in the code. This enables the weighting of a function on the pseudo-polar grid to simply be a point-wise multiplication in each sampling point. That is, letting  $J := \hat{I} : \Omega_R \rightarrow \mathbb{C}$  be the pseudo-polar Fourier transform of an  $N \times N$  image  $I$  and  $w : \Omega_R \rightarrow \mathbb{R}^+$  be any suitable weight function on  $\Omega_R$ , the values

$$J_w(\omega_1, \omega_2) = J(\omega_1, \omega_2) \cdot \sqrt{w(\omega_1, \omega_2)} \quad \text{for all } (\omega_1, \omega_2) \in \Omega_R$$

need to be computed.

Let us comment on why the square root of the weight is utilized. If the weights  $w$  satisfy the condition in Theorem 2.1, we obtain  $P^* w P = \text{Id}$ , which can be written in a symmetric form as follows:  $(\sqrt{w}P)^* \sqrt{w}P = \text{Id}$ . This form shows that the operator  $\sqrt{w}P$  can be inverted by taking the adjoint  $(\sqrt{w}P)^*$ . In other words, each image can be reconstructed from its weighted pseudo-polar Fourier transform by applying the adjoint of the weighted pseudo-polar Fourier transform. This issue will be discussed in further detail in Subsection 2.4.2.

## 2.3 Digital Shearlets on Pseudo-Polar Grid

We next aim at deriving a faithful digitization of the shearlet transform associated with a band-limited cone-adapted discrete shearlet system to the pseudo-polar grid. This would settle Step (S3).

### 2.3.1 Preparation for Faithful Digitization

For this, let us recall the definition of the discrete shearlet transform associated with (2.2); taking the particular form (2.1) of the shearlet  $\psi \in L^2(\mathbb{R}^2)$  into account. Restricting our attention to the cone  $\mathcal{C}_{21}$ , we obtain

$$\begin{aligned} f &\mapsto \left\langle \hat{f}, 2^{-j\frac{3}{2}} \hat{\psi}(S_k^T A_{4^{-j}} \cdot) \chi_{\mathcal{C}_{21}} e^{2\pi i \langle A_{4^{-j}} S_k m, \cdot \rangle} \right\rangle \\ &= \left\langle \hat{f}, 2^{-j\frac{3}{2}} \hat{\psi}_1(4^{-j} \xi_1) \hat{\psi}_2(k + 2^j \frac{\xi_2}{\xi_1}) \chi_{\mathcal{C}_{21}} e^{2\pi i \langle A_{4^{-j}} S_k m, \cdot \rangle} \right\rangle, \end{aligned}$$

for scale  $j$ , orientation  $k$ , position  $m$ , and cone  $\iota$ .

To approach a faithful digitization, we first have to partition  $\Omega_R$  according to the partitioning of the plane into  $\mathcal{C}_{11}$ ,  $\mathcal{C}_{12}$ ,  $\mathcal{C}_{21}$ , and  $\mathcal{C}_{22}$ , as well as a centered rectangle  $\mathcal{R}$ . The center  $\mathcal{C}$  as defined in (2.6) will play the role of  $\mathcal{R}$ . Thus it remains to partition the set  $\Omega_R$  beyond the already defined partitioning into  $\Omega_R^1$  and  $\Omega_R^2$  (cf. (2.4) and (2.5)) by setting

$$\Omega_R^1 = \Omega_R^{11} \cup \mathcal{C} \cup \Omega_R^{12} \quad \text{and} \quad \Omega_R^2 = \Omega_R^{21} \cup \mathcal{C} \cup \Omega_R^{22},$$

where

$$\begin{aligned}
\Omega_R^{11} &= \left\{ \left( -\frac{2n}{R} \cdot \frac{2\ell}{N}, \frac{2n}{R} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, 1 \leq n \leq \frac{RN}{2} \right\}, \\
\Omega_R^{12} &= \left\{ \left( -\frac{2n}{R} \cdot \frac{2\ell}{N}, \frac{2n}{R} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, -\frac{RN}{2} \leq n \leq -1 \right\}, \\
\Omega_R^{21} &= \left\{ \left( \frac{2n}{R}, -\frac{2n}{R} \cdot \frac{2\ell}{N} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, 1 \leq n \leq \frac{RN}{2} \right\} \\
\Omega_R^{22} &= \left\{ \left( \frac{2n}{R}, -\frac{2n}{R} \cdot \frac{2\ell}{N} \right) : -\frac{N}{2} \leq \ell \leq \frac{N}{2}, -\frac{RN}{2} \leq n \leq -1 \right\}.
\end{aligned}$$

When restricting to the cone  $\Omega_R^{21}$ , say, the exact digitization of the coefficients of the discrete shearlet system is

$$\begin{aligned}
&\sum_{\omega := (\omega_1, \omega_2) \in \Omega_R^{21}} J(\omega_1, \omega_2) 2^{-j\frac{3}{2}} \overline{\widehat{\psi}(S_k^T A_{4^{-j}} \omega)} e^{-2\pi i \langle A_{4^{-j}} S_k m, \omega \rangle} \\
&= \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} J(\omega_1, \omega_2) 2^{-j\frac{3}{2}} \overline{W(4^{-j} \omega_x) V(k + 2^j \frac{\omega_2}{\omega_1})} e^{-2\pi i \langle A_{4^{-j}} S_k m, \omega \rangle} \\
&= \sum_{n=1}^{\frac{RN}{2}} \sum_{\ell=-\frac{N}{2}}^{\frac{N}{2}} J(\omega_1, \omega_2) 2^{-j\frac{3}{2}} \overline{W(4^{-j} \frac{2n}{R}) V(k - 2^{j+1} \frac{\ell}{N})} e^{-2\pi i \langle m, S_k^T A_{4^{-j}} \omega \rangle}, \quad (2.13)
\end{aligned}$$

where  $V$  and  $W$  as well as the ranges of  $j$ ,  $k$ , and  $m$  are to be carefully chosen.

Our main objective will be to achieve a digital shearlet transform, which is an isometry. This – as in the continuum domain situation – is equivalent to requiring the associated shearlet system to form a tight frame for functions  $J : \Omega_R \rightarrow \mathbb{C}$ . For the convenience of the reader let us recall the notion of a Parseval frame in this particular situation. A sequence  $(\varphi_\lambda)_{\lambda \in \Lambda} - \Lambda$  being some indexing set – is a *tight frame* for all functions  $J : \Omega_R \rightarrow \mathbb{C}$ , if

$$\sum_{\lambda \in \Lambda} \left| \sum_{(\omega_1, \omega_2) \in \Omega_R} J(\omega_1, \omega_2) \overline{\varphi_\lambda(\omega_1, \omega_2)} \right|^2 = \sum_{(\omega_1, \omega_2) \in \Omega_R} |J(\omega_1, \omega_2)|^2.$$

In the sequel we will define digital shearlets on  $\Omega_R^{21}$  and extend the definition to the other cones by symmetry.

### 2.3.2 Subband Windows on the Pseudo-Polar Grid

We start by defining the scaling function, which will depend on two functions  $V_0$  and  $W_0$ , and the generating digital shearlet, which will depend on again two functions  $V$  and  $W$ .  $W_0$  and  $W$  will be chosen to be Fourier transforms of wavelets, and  $V_0$  and  $V$  will be chosen to be ‘bump’ functions, paralleling the construction of classical shearlets.

First, let  $W_0$  be the Fourier transform of the Meyer scaling function such that

$$\text{supp } W_0 \subseteq [-1, 1] \quad \text{and} \quad W_0(\pm 1) = 0, \quad (2.14)$$

and let  $V_0$  be a ‘bump’ function satisfying

$$\text{supp } V_0 \subseteq [-3/2, 3/2] \quad \text{with} \quad V_0(\xi) \equiv 1 \text{ for } |\xi| \leq 1, \xi \in \mathbb{R}.$$

Then we define the *scaling function*  $\phi$  for the digital shearlet system to be

$$\hat{\phi}(\xi_1, \xi_2) = W_0(4^{-j\ell} \xi_1) V_0(4^{-j\ell} \xi_2), \quad (\xi_1, \xi_2) \in \mathbb{R}^2.$$

For now, we define it in continuum domain, and will later restrict this function to the pseudo-polar grid.

Let next  $W$  be the Fourier transform of the Meyer wavelet function satisfying the support constraints

$$\text{supp } W \subseteq [-4, 1/4] \cup [1/4, 4] \quad \text{and} \quad W(\pm 1/4) = W(\pm 4) = 0, \quad (2.15)$$

as well as, choosing the lowest scale  $j_L$  to be  $j_L := -\lceil \log_4(R/2) \rceil$ ,

$$|W_0(4^{-j_L} \xi)|^2 + \sum_{j=j_L}^{\lceil \log_4 N \rceil} |W(4^{-j} \xi)|^2 = 1 \quad \text{for all } |\xi| \leq N, \xi \in \mathbb{R}. \quad (2.16)$$

We further choose  $V$  to be a ‘bump’ function satisfying

$$\text{supp } V \subseteq [-1, 1] \quad \text{and} \quad V(\pm 1) = 0, \quad (2.17)$$

as well as

$$|V(\xi - 1)|^2 + |V(\xi)|^2 + |V(\xi + 1)|^2 = 1 \quad \text{for all } |\xi| \leq 1, \xi \in \mathbb{R}. \quad (2.18)$$

Then the *generating shearlet*  $\psi$  for the digital shearlet system on  $\Omega_R^2$  is defined as

$$\hat{\psi}(\xi_1, \xi_2) = W(\xi_1) V\left(\frac{\xi_2}{\xi_1}\right), \quad (\xi_1, \xi_2) \in \mathbb{R}^2. \quad (2.19)$$

Notice that (2.18) implies

$$\sum_{s=-2^j}^{2^j} |V(2^j \xi - s)|^2 = 1 \quad \text{for all } |\xi| \leq 1, \xi \in \mathbb{R}; j \geq 0, \quad (2.20)$$

which will become important for the analysis of frame properties. For the particular choice of  $V_0, W_0, V$ , and  $W$  in `ShearLab`, we refer to Subsection 2.3.7.

### 2.3.3 Range of Parameters

We from now on assume that  $R$  and  $N$  are both positive even integers and that  $N = 2^{n_0}$  for some integer  $n_0 \in \mathbb{N}$ . This poses no restrictions, since both parameters can be enlarged to satisfy this condition.

We start by analyzing the range of  $j$ . Recalling the definition of the shearlet  $\psi$  in (2.19) and the support properties of  $W$  and  $V$  in (2.15) and (2.17), respectively, we observe that the digitized shearlet

$$2^{-j\frac{3}{2}} W(4^{-j} \frac{2n}{R}) V(k - 2^{j+1} \frac{\ell}{N}) e^{2\pi i \langle m, S_k^T A_{4^{-j}} \omega \rangle} \quad (2.21)$$

from (2.13) has radial support

$$n = 4^{j-1} \frac{R}{2} + t_1, \quad t_1 = 0, \dots, 4^{j-1} \cdot \frac{15R}{2} \quad (2.22)$$

on the cone  $\Omega_R^{21}$ . To determine the appropriate range of  $j$ , we will analyze the precise support in radial direction. If  $j < -\lceil \log(R/2) \rceil$ , then  $n < 1$ , which corresponds to only one point – the origin – and is dealt with by the scaling function. If  $j > \lceil \log_4 N \rceil$ , we have  $n \geq \frac{RN}{2}$ . Hence the value  $W(1/4) = 0$  (cf. (2.15)) is placed on the boundary, and these scales can be omitted. Therefore, the range of the scaling parameter will be chosen to be

$$j \in \{j_L, \dots, j_H\}, \quad \text{where } j_L := -\lceil \log(R/2) \rceil \text{ and } j_H := \lceil \log_4 N \rceil.$$

Next, we determine the appropriate range of  $k$ . Again recalling the definition of the shearlet  $\psi$  in (2.19), the digitized shearlet (2.21) has angular support

$$\ell = 2^{-j-1} N(k-1) + t_2, \quad t_2 = 0, \dots, 2^{-j} N \quad (2.23)$$

on the cone  $\Omega_R^{21}$ . To compute the range of  $k$ , we start by examining the case  $j \geq 0$ . If  $k > 2^j$ , we have  $\ell \geq N/2$ . Hence the value  $V(-1) = 0$  (cf. (2.17)) is placed on the seam line, and these parameters can be omitted. By symmetry, we also obtain  $k \geq -2^j$ . Thus the shearing parameter will be chosen to be

$$k \in \{-2^j, \dots, 2^j\}.$$

### 2.3.4 Support Size of Shearlets

We next compute the support as well as the support size of scaled and sheared version of digital shearlets. This will be used for the normalization of digital shearlets.

As before, we first analyze the radial support. By (2.22), the radial supports of the windows associated with scales  $j_L < j < j_H$  is

$$n = 4^{j-1} \frac{R}{2} + t_1, \quad t_1 = 0, \dots, 4^{j-1} \cdot \frac{15R}{2}, \quad (2.24)$$

and the radial support of the windows associated with the scale  $j_L = -\lceil \log_4(R/2) \rceil$  and  $j_H = \lceil \log_4 N \rceil$  are

$$\begin{aligned} n = t_1, \quad t_1 = 1, \dots, 4^{j_L+1} \frac{R}{2}, \quad & \text{for } j = j_L, \\ n = 4^{j_H-1} \frac{R}{2} + t_1, \quad t_1 = 0, \dots, \frac{RN}{2} - 4^{j_H-1} \frac{R}{2}, \quad & \text{for } j = j_H. \end{aligned} \quad (2.25)$$

Turning to the angular direction, by (2.23), the angular support of the windows at scale  $j$  associated with shears  $-2^j < k < 2^j$  is

$$\ell = 2^{-j-1}N(k-1) + t_2, \quad t_2 = 0, \dots, 2^{-j}N, \quad (2.26)$$

the angular support at scale  $j$  associated with the shear parameter  $k = -2^j$  is

$$\ell = 2^{-j-1}N(-2^j - 1) + t_2, \quad t_2 = 2^{-j} \frac{N}{2}, \dots, 2^{-j}N,$$

and for  $k = 2^j$  it is

$$\ell = 2^{-j-1}N(2^j - 1) + t_2, \quad t_2 = 0, \dots, 2^{-j} \frac{N}{2}. \quad (2.27)$$

For the case  $j < 0$ , we simply let  $k = 0$  and  $\ell = -N/2 + t_2$  with  $t_2 = 0, \dots, N$ . Also, for this lower frequency case, the window function  $W(4^{-j}\omega_1)V(k + 2^j \frac{\omega_2}{\omega_1})$  is slightly modified to be  $W(4^{-j}\omega_1)V_0(k + 2^j \frac{\omega_2}{\omega_1})$ .

These computations now allow us to determine the support size of the function  $W(4^{-j}\omega_1)V(k + 2^j \frac{\omega_2}{\omega_1})$  in terms of pairs  $(n, \ell)$ , which for scale  $j$  and shear  $k$ , is

$$\mathcal{L}_j^1 = \begin{cases} 4^{j+1} \frac{R}{2} & : j = j_L, \\ 4^{j-1} \cdot \frac{15R}{2} + 1 & : j_L < j < j_H, \\ \frac{RN}{2} - 4^{j-1} \frac{R}{2} + 1 & : j = j_H, \end{cases} \quad (2.28)$$

and

$$\mathcal{L}_{j,k}^2 = \begin{cases} 2^{-j}N + 1 & : -2^j < k < 2^j \text{ with } j \geq 0, \\ 2^{-j} \frac{N}{2} + 1 & : k \in \{-2^j, 2^j\} \text{ with } j \geq 0, \\ N + 1 & : j < 0. \end{cases} \quad (2.29)$$

### 2.3.5 Digitization of the Exponential Term

We next digitize the exponential term in (2.21), which can be rewritten as

$$e^{-2\pi i \langle m, S_k^T A_{4^{-j}} \omega \rangle} = e^{-2\pi i \langle m, (4^{-j}\omega_1, 4^{-j}k\omega_1 + 2^{-j}\omega_2) \rangle} = e^{-2\pi i \langle m, (4^{-j} \frac{2n}{R}, 4^{-j}k \frac{2n}{R} - 2^{-j} \frac{4\ell n}{RN}) \rangle}.$$

We observe two obstacles:

- The change of variables  $\tau := S_k^T A_{4^{-j}} \omega$  possible in (2.13) can not be performed similarly in this situation due to the fact that the pseudo-polar grid is *not* invariant under the action of  $S_k^T A_{4^{-j}}$ . This is however the first step in the continuum domain reasoning for tightness; see Chapter [1].
- The Fourier transform of a function defined on the pseudo-polar grid does *not* satisfy any Plancherel theorem.

These problems require a slight adjustment of the exponential term, which will be the only adaption we allow us to make when digitizing. This will circumvent the two obstacles and enable us to construct a Parseval frame as well as derive a direct application of the inverse Fast Fourier transform in FDST.

The adjustment will be made by using the mapping  $\theta : \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$  defined by  $\theta(x, y) = (x, \frac{y}{x})$ . This yields the modified exponential term

$$e^{-2\pi i \langle m, (\theta \circ (S_k^T)^{-1})(4^{-j} \frac{2n}{R}, 4^{-j} k \frac{2n}{R} - 2^{-j} \frac{4n}{RN}) \rangle} = e^{-2\pi i \langle m, (4^{-j} \frac{2n}{R}, -2^{j+1} \frac{\ell}{N}) \rangle}, \quad (2.30)$$

which can be rewritten as

$$e^{-2\pi i \langle m, (4^{-j} \frac{2n}{R}, -2^{j+1} \frac{\ell}{N}) \rangle} = e^{-2\pi i (\frac{m_1}{4} + (1-k)m_2)} e^{-2\pi i \langle m, (4^{-j} \frac{2t_1}{R}, -2^{j+1} \frac{t_2}{N}) \rangle},$$

with  $t_1$  and  $t_2$  ranging over an appropriate set defined by (2.24), (2.25), and (2.26)–(2.27). Fig. 3 illustrates this adjustment.

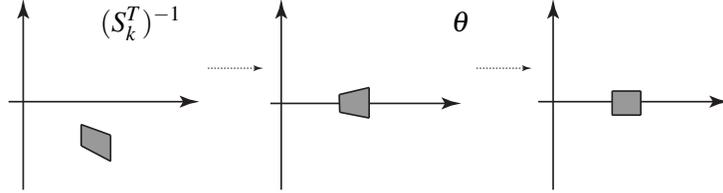


Figure 3: Adjustment of the exponential term through the map  $\theta \circ (S_k^T)^{-1}$ .

Now, taking into account of the support size of each  $W(4^{-j} \omega_1) V(k + 2^j \frac{\omega_2}{\omega_1})$  as given in (2.28) and (2.29), we obtain the following reformulation of (2.30):

$$\exp \left\{ -2\pi i \left\langle m, \left( \frac{\mathcal{L}_j^1 4^{-j} (2/R)}{\mathcal{L}_j^1} t_1, \frac{-\mathcal{L}_{j,k}^2 2^{j+1} (1/N)}{\mathcal{L}_{j,k}^2} t_2 \right) \right\rangle \right\}, \quad t_1, t_2. \quad (2.31)$$

This version shows that we might regard the exponential terms as characters of a suitable locally compact abelian group (see [18]) with associated annihilator identified with the rectangle

$$\mathcal{R}_{j,k} = \left\{ \left( \frac{4^j \frac{R}{2} \cdot r_1}{\mathcal{L}_j^1}, -\frac{N}{2^{j+1}} \cdot r_2 \right) : r_1 = 0, \dots, \mathcal{L}_j^1 - 1, r_2 = 0, \dots, \mathcal{L}_{j,k}^2 - 1 \right\},$$

where  $\mathcal{L}_j^1$  and  $\mathcal{L}_{j,k}^2$  were defined in (2.28) and (2.29), respectively. This viewpoint will be crucial to guarantee that the digital shearlet system defined in Subsection 2.3.6 provides a Parseval frame on the pseudo-polar grid  $\Omega_R$ . In practice, (2.31) also ensures that in Step (S3) on each windowed image on the pseudo-polar grid only a 2D-iFFT – in contrast to a fractional Fourier transform – needs to be performed, thereby reducing the computational complexity.

For the low frequency square, we further require the set

$$\mathcal{R} = \{(r_1, r_2) : r_1 = -1, \dots, 1, r_2 = -\frac{N}{2}, \dots, \frac{N}{2}\},$$

which will be shown to be sufficient for guaranteeing that digital shearlet system forms a Parseval frame.

### 2.3.6 Digital Shearlets

We are now ready to define digital shearlets, which we define as functions on the pseudo-polar grid  $\Omega_R$ . The spatial domain picture can thus be derived by the inverse pseudo-polar Fourier transform.

**Definition 2.2.** *Retaining the definitions and notations from Subsection 2.3, for all  $(\omega_1, \omega_2) \in \Omega_R^{21}$ , we define digital shearlets at scale  $j \in \{j_L, \dots, j_H\}$ , shear  $k = [-2^j, 2^j] \cap \mathbb{Z}$ , and spatial position  $m \in \mathcal{R}_{j,k}$  by*

$$\sigma_{j,k,m}^{21}(\omega_1, \omega_2) = \frac{C(\omega_1, \omega_2)}{\sqrt{|\mathcal{R}_{j,k}|}} W(4^{-j}\omega_1) V^j(k + 2^j \frac{\omega_2}{\omega_1}) \chi_{\Omega_R^{21}}(\omega_1, \omega_2) e^{2\pi i \langle m, (4^{-j}\omega_1, 2^j \frac{\omega_2}{\omega_1}) \rangle},$$

where  $V^j = V$  for  $j \geq 0$  and  $V^j = V_0$  for  $j < 0$ , and

$$C(\omega_1, \omega_2) = \begin{cases} 1 & : (\omega_1, \omega_2) \notin \mathcal{S}_R^1 \cup \mathcal{S}_R^2, \\ \frac{1}{\sqrt{2}} & : (\omega_1, \omega_2) \in (\mathcal{S}_R^1 \cup \mathcal{S}_R^2) \setminus \mathcal{C}, \\ \frac{1}{\sqrt{2(N+1)}} & : (\omega_1, \omega_2) \in \mathcal{C}. \end{cases}$$

The shearlets  $\sigma_{j,k,m}^{11}, \sigma_{j,k,m}^{12}, \sigma_{j,k,m}^{22}$  on the remaining cones are defined accordingly by symmetry with equal indexing sets for scale  $j$ , shear  $k$ , and spatial location  $m$ . For  $\iota_0 = 1, 2$ ,  $(\omega_1, \omega_2) \in \Omega_R^{\iota_0}$ , and  $n_0 \in \mathcal{R}$ , we define the scaling function

$$\varphi_{n_0}^{\iota_0}(\omega_1, \omega_2) = \frac{C(\omega_1, \omega_2)}{\sqrt{|\mathcal{R}|}} \hat{\phi}(\omega_1, \omega_2) \chi_{\Omega_R^{\iota_0}}(\omega_1, \omega_2) e^{2\pi i \langle n_0, (\frac{n}{3}, \frac{\ell}{N+1}) \rangle}.$$

Then the digital shearlet system *DSH* is defined by

$$\begin{aligned} DSH = \{ \varphi_{n_0}^{\iota_0} : \iota_0 = 1, 2, n_0 \in \mathcal{R} \} \cup \{ \sigma_{j,k,m}^{\iota} : j \in \{j_L, \dots, j_H\}, k \in \{-2^j, 2^j\}, \\ m \in \mathcal{R}_{j,s}, \iota = 11, 12, 21, 22 \}. \end{aligned}$$

As desired, the digital shearlet system *DSH*, which we derived as a faithful digitization of the continuum domain band-limited cone-adapted discrete shearlet system, forms a Parseval frame for  $J : \Omega_R \rightarrow \mathbb{C}$ .

**Theorem 2.2** ([20]). *The digital shearlet system *DSH* defined in Definition 2.2 forms a Parseval frame for functions  $J : \Omega_R \rightarrow \mathbb{C}$ .*

*Proof.* Letting  $J : \Omega_R \rightarrow \mathbb{C}$ , we claim that

$$\langle J, J \rangle_{\Omega_R} = \sum_{\iota_0, n_0} |\langle J, \varphi_{n_0}^{\iota_0} \rangle_{\Omega_R}|^2 + \sum_{\iota, j, k, m} |\langle J, \sigma_{j,k,m}^{\iota} \rangle_{\Omega_R}|^2 \quad (2.32)$$

which proves the result. Here  $\langle J_1, J_2 \rangle_{\Omega_R} := \sum_{(\omega_1, \omega_2) \in \Omega_R} J_1(\omega_1, \omega_2) \overline{J_2(\omega_1, \omega_2)}$  for  $J_1, J_2 : \Omega_R \rightarrow \mathbb{C}$ .

We start by analyzing the first term on the RHS of (2.32). Let  $\iota_0 \in \{1, 2\}$  and  $J_C : \Omega_R \rightarrow \mathbb{C}$  be defined by  $J_C(\omega_1, \omega_2) := C(\omega_1, \omega_2) \cdot J(\omega_1, \omega_2)$  for  $(\omega_1, \omega_2) \in \Omega_R$ . Using the support conditions of  $\hat{\phi}$ ,

$$\begin{aligned} \sum_n |\langle J, \varphi_{n_0}^{\iota_0} \rangle_{\Omega_R}|^2 &= \sum_{n_0} \left| \sum_{(\omega_1, \omega_2) \in \Omega_R^{\iota_0}} J(\omega_1, \omega_2) \overline{\varphi_{n_0}^{\iota_0}(\omega_1, \omega_2)} \right|^2 \\ &= \frac{1}{|\mathcal{R}|} \sum_{n_0} \left| \sum_{(\omega_1, \omega_2) \in \Omega_R^{\iota_0}} J_C(\omega_1, \omega_2) \cdot \hat{\phi}(\omega_1, \omega_2) \cdot e^{-2\pi i \langle n_0, (\frac{n}{3}, \frac{\ell}{N+1}) \rangle} \right|^2 \\ &= \frac{1}{|\mathcal{R}|} \sum_{n_0} \left| \sum_{n=-1}^1 \sum_{\ell=-N/2}^{N/2} J_C(\omega_1, \omega_2) \cdot \hat{\phi}(\omega_1, \omega_2) \cdot e^{-2\pi i \langle n_0, (\frac{n}{3}, \frac{\ell}{N+1}) \rangle} \right|^2. \end{aligned}$$

The choice of  $\mathcal{R}$  now allows us to use the Plancherel formula, see Subsection 2.3.5. Exploiting again support properties (see Subsection 2.3.5), we conclude that

$$\sum_n |\langle J, \varphi_n^{t_0} \rangle_{\Omega_R}|^2 = \sum_{(\omega_1, \omega_2) \in \Omega_R^{t_0}} |C(\omega_1, \omega_2) \cdot J(\omega_1, \omega_2)|^2 \cdot |\hat{\phi}(\omega_1, \omega_2)|^2.$$

Combining  $t_0 = 1, 2$  and using (2.14), we proved

$$\sum_{t_0} \sum_{n_0} |\langle J, \varphi_{n_0}^{t_0} \rangle_{\Omega_R}|^2 = \sum_{(\omega_1, \omega_2) \in \Omega_R} |J(\omega_1, \omega_2)|^2 \cdot |W_0(\omega_1)|^2. \quad (2.33)$$

Next we study the second term on the RHS in (2.32). By symmetry, it suffices to consider the case  $t = 21$ . By the support conditions on  $W$  and  $V$  (see (2.15) and (2.17)),

$$\begin{aligned} & \sum_{j,k,m} |\langle J, \sigma_{j,k,m}^{21} \rangle_{\Omega_R}|^2 = \sum_{j,k} \sum_{m \in \mathcal{R}_{j,k}} \left| \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} J(\omega_1, \omega_2) \overline{\sigma_{j,k,m}^{21}(\omega_1, \omega_2)} \right|^2 \\ &= \sum_{j,k} \frac{1}{|\mathcal{R}_{j,k}|} \sum_{m \in \mathcal{R}_{j,k}} \left| \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} J_C(\omega_1, \omega_2) \cdot \overline{W(4^{-j}\omega_1)} \right. \\ & \quad \left. \cdot \overline{V^j(k + 2^j \frac{\omega_2}{\omega_1})} \cdot e^{-2\pi i \langle m, (4^{-j}\omega_1, 2^j \frac{\omega_2}{\omega_1}) \rangle} \right|^2 \\ &= \sum_{j,k} \frac{1}{|\mathcal{R}_{j,k}|} \sum_{m \in \mathcal{R}_{j,k}} \left| \sum_{n=4^{j-1}(R/2)}^{4^{j+1}(R/2)} \sum_{\ell=2^{-j-1}N(k-1)}^{2^{-j-1}N(k+1)} J_C(\omega_1, \omega_2) \right. \\ & \quad \left. \cdot \overline{W(4^{-j}\omega_1)} \cdot \overline{V^j(k + 2^j \frac{\omega_2}{\omega_1})} \cdot e^{-2\pi i \langle m, (4^{-j} \frac{2n}{R}, -2^{j+1} \frac{\ell}{N}) \rangle} \right|^2. \end{aligned}$$

Similarly as before, the choice of  $\mathcal{R}_{j,k}$  does allow us to use the Plancherel formula, see Subsection 2.3.5. Hence,

$$\sum_{j,k,m} |\langle J, \sigma_{j,k,m}^{21} \rangle_{\Omega_R}|^2 = \sum_{j,k} \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} \left| J_C(\omega_1, \omega_2) \cdot \overline{W(4^{-j}\omega_1)} \overline{V^j(k + 2^j \frac{\omega_2}{\omega_1})} \right|^2.$$

Next we use (2.20) to obtain

$$\begin{aligned} & \sum_{j,k} \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} \left| J_C(\omega_1, \omega_2) \cdot \overline{W(4^{-j}\omega_1)} \cdot \overline{V^j(k + 2^j \frac{\omega_2}{\omega_1})} \right|^2 \\ &= \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} |J_C(\omega_1, \omega_2)|^2 \sum_{j=j_L}^{j_H} |W(4^{-j}\omega_1)|^2 \cdot \sum_{k=-2^j}^{2^j} |V^j(k + 2^j \frac{\omega_2}{\omega_1})|^2 \\ &= \sum_{(\omega_1, \omega_2) \in \Omega_R^{21}} |J_C(\omega_1, \omega_2)|^2 \sum_{j=j_L}^{j_H} |W(4^{-j}\omega_1)|^2. \end{aligned}$$

Thus the second term on the RHS in (2.32) equals

$$\sum_t \sum_{j,k,m} |\langle J, \sigma_{j,k,m}^t \rangle_{\Omega_R}|^2 = \sum_{(\omega_1, \omega_2) \in \Omega_R} |J(\omega_1, \omega_2)|^2 \cdot \sum_{j=j_L}^{j_H} |W(4^{-j}\omega_1)|^2. \quad (2.34)$$

Finally, our claim (2.32) follows from combining (2.33), (2.34), and (2.16).  $\square$   $\square$

### 2.3.7 Digital Shearlet Windowing

The final Step (S3) of the FDST then consists in decomposing the data on the points of the pseudo-polar grid given by the previously – in Steps (S1) and (S2) – computed weighted pseudo-polar image  $J_w : \Omega_R \rightarrow \mathbb{C}$  into rectangular subband windows according to the digital shearlet system DSH defined in Definition 2.2, followed by a 2D-iFFT. More precisely, given  $J_w$ , the set of digital shearlet coefficients

$$c_{n_0}^{t_0} := \langle J_w, \varphi_{n_0}^{t_0} \rangle_{\Omega_R} \quad \text{for all } t_0, n_0$$

and

$$c_{j,k,m}^l := \langle J_w, \sigma_{j,k,m}^l \rangle_{\Omega_R} \quad \text{for all } j, k, m, l$$

is computed followed by application of the 2D-iFFT to each windowed image  $J_w \varphi_0^{t_0}$  and  $J_w \sigma_{j,k,0}^l$  restricted on the support of  $\varphi_0^{t_0}$  and  $\sigma_{j,k,0}^l$ , respectively.

The definition of the digital shearlet system DSH in Definition 2.2 requires appropriate choices of the functions  $\phi$ ,  $V_0$ ,  $V$ ,  $W_0$ , and  $W$ , and the required conditions are stated throughout Subsection 2.3.2. We now discuss one particular choice, which is chosen in `ShearLab`. We start selecting the ‘wavelets’  $W_0$  and  $W$ . In Subsection 2.3.2, these functions were defined to be Fourier transforms of the Meyer scaling function and wavelet function, respectively, i.e.,

$$W_0(\xi) = \begin{cases} 1 & : |\xi| \leq \frac{1}{4}, \\ \cos \left[ \frac{\pi}{2} \nu \left( \frac{4}{3} |\xi| - \frac{1}{3} \right) \right] & : \frac{1}{4} \leq |\xi| \leq 1, \\ 0 & : \text{otherwise,} \end{cases}$$

and

$$W(\xi) = \begin{cases} \sin \left[ \frac{\pi}{2} \nu \left( \frac{4}{3} |\xi| - \frac{1}{3} \right) \right] & : \frac{1}{4} \leq |\xi| \leq 1, \\ \cos \left[ \frac{\pi}{2} \nu \left( \frac{1}{3} |\xi| - \frac{1}{3} \right) \right] & : 1 \leq |\xi| \leq 4, \\ 0 & : \text{otherwise,} \end{cases}$$

where  $\nu \geq 0$  is a  $C^k$  function or  $C^\infty$  function such that  $\nu(x) + \nu(1-x) = 1$  for  $0 \leq x \leq 1$ . One possible choice for  $\nu$  is the function  $\nu(x) = x^4(35 - 84x + 70x^2 - 20x^3)$ ,  $0 \leq x \leq 1$ , which then automatically fixes  $W_0$  and  $W$ . Since  $|W_0(\xi)|^2 + |W(\xi)|^2 = 1$  for  $|\xi| \leq 1$ , the required condition (2.16) is satisfied. The function  $\nu$  can be also used to design the ‘bump’ function  $V$  as well, which needs to satisfy (2.18). One possible choice for  $V$  is to define it by  $V(\xi) = \sqrt{\nu(1+\xi) + \nu(1-\xi)}$ ,  $-1 \leq \xi \leq 1$ .  $V_0$  can then simply be chosen as  $V_0 \equiv 1$ . Let us finally mention that  $\phi$  is defined depending on  $V_0$  and  $W_0$ , wherefore fixing these two functions determines  $\phi$  uniquely.

## 2.4 Algorithmic Realization of the FDST

We have previously discussed all main ingredients of the fast digital shearlet transform (FDST) – Fast PPFT, Weighting, and Digital Shearlet Windowing –, and will now summarize those findings. Depending on the application at hand, a fast inverse transform is required, which we will also detail in the sequel. In fact, we will present two possibilities: the Adjoint FDST and the Inverse FDST depending on whether the weighting allows to use the adjoint for reconstruction or whether an iterative procedure is required for higher accuracy. Fig. 4 provides an overview of the main steps of the FDST and its inverse. For a more detailed description of FDST, Adjoint FDST, and Inverse FDST in form of pseudo-code, we refer to [20].

For the sake of brevity, we now let  $P$ ,  $w$ , and  $W$  denote the Fast PPFT from Subsection 2.1.2, the weighting on the pseudo-polar grid described in Subsection 2.2.3, and windowing operator consisting of the application of the shearlet windows followed by 2D-iFFT to each array as detailed in Subsection 2.3.7, respectively.

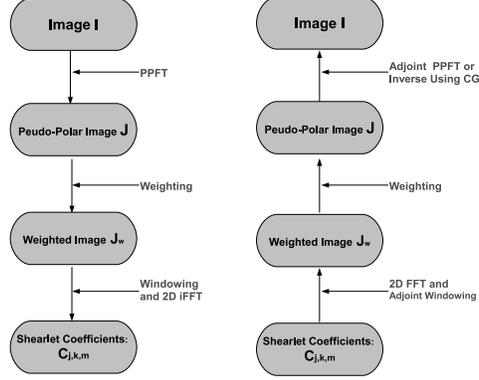


Figure 4: Flowcharts of the FDST (left) and its inverse (right).

### 2.4.1 FDST

We can summarize the steps of the algorithm FDST as follows:

- **Step (S1):** For a given image  $I$ , apply the Fast PPFT as described in Subsection 2.1.2 to obtain the function  $PI : \Omega_R \rightarrow \mathbb{C}$ .
- **Step (S2):** Apply the square root of an off-line computed weight function  $w : \Omega_R \rightarrow \mathbb{C}$  to  $PI$  as described in Subsection 2.2.3, yielding  $\sqrt{w}PI : \Omega_R \rightarrow \mathbb{C}$ .
- **Step (S3):** Apply the shearlet windows to the function  $wPI$ , followed by a 2D-iFFT to each array to obtain the shearlet coefficients  $W\sqrt{w}PI$ , which we denote by  $c_{n_0}^{l_0}$ ,  $l_0, n_0$  and  $c_{j,k,m}^l$ ,  $j, k, m, l$ .

### 2.4.2 Adjoint FDST

Assuming that the weight function  $w$  used in Step (S2) satisfies the condition in Theorem 2.1, and using the Parseval frame property of the digital shearlet system (Theorem 2.2), we obtain

$$(W\sqrt{w}P)^*W\sqrt{w}P = P^*\sqrt{w}(W^*W)\sqrt{w}P = P^*wP = Id.$$

Hence in this case, the FDST, which is abbreviated by  $W\sqrt{w}P$  can be inverted by applying the adjoint FDST, which cascades the following steps:

- **Step 1:** For given shearlet coefficients  $C$ , i.e.,  $c_{n_0}^{l_0}$ ,  $l_0, n_0$  and  $c_{j,k,m}^l$ ,  $j, k, m, l$ , compute the linear combination of the shearlet windows with coefficients  $c_{n_0}^{l_0}$ ,  $l_0, n_0$  and  $c_{j,k,m}^l$ ,  $j, k, m, l$ . This gives the function  $W^*C : \Omega_R \rightarrow \mathbb{C}$ .
- **Step 2:** Apply the square root of an off-line computed weight function  $w : \Omega_R \rightarrow \mathbb{C}$  to  $W^*C$ , yielding the function  $\sqrt{w}W^*C : \Omega_R \rightarrow \mathbb{C}$ .
- **Step 3:** Apply the Fast Adjoint PPFT by running the Fast PPFT ‘backwards’. For this, we just notice that the adjoint fractional Fourier transform of a vector  $c \in \mathbb{C}^{N+1}$  with respect to a constant  $\alpha \in \mathbb{C}$  is given by  $F_{N+1}^{-\alpha}c$ . Also, for  $m > N$ , the adjoint padding operator  $E_{m,N}^*$  applied to a vector  $c \in \mathbb{C}^m$  is given by  $(E_{m,N}^*c)(k) = c(k)$ ,  $k = -N/2, \dots, N/2 - 1$ . The Adjoint PPFT gives an image  $P^*\sqrt{w}W^*C$ .

### 2.4.3 Inverse FDST

Normally – as also with the relaxed form of weights debated in Subsection 2.2.2 – the weights will not satisfy the conditions of Theorem 2.1 precisely. A measure for whether application of the adjoint is still feasible will be discussed in Subsection 4.2. If higher accuracy of the reconstruction is required, one might use iterative methods, such as conjugate gradient methods. Since the digital shearlet system forms a Parseval frame, we always have

$$W^*W\sqrt{w}P = \sqrt{w}P.$$

Hence, iterative methods need to be ‘only’ applied to reconstruct an image  $I$  from knowledge of  $J := \sqrt{w}PI$ , i.e., to solve the equation

$$P^*wPI = P^*wJ$$

for  $I$ . Since  $J$  might not be in the range of  $P$ ,  $I$  is typically computed by solving the weighted least square problem  $\min_I \|\sqrt{w}PI - \sqrt{w}J\|_2$ . Since the matrix corresponding to  $P^*P$  is symmetric positive definite, iterative methods such as the conjugate gradient method are applicable. The conjugate gradient method is then applied to the equation  $Ax = b$  with  $A = P^*wP$  and  $b = P^*wJ$ . Its performance can be measured by the condition number of the operator  $P^*wP$ :  $\text{cond}(P^*wP) = \lambda_{\max}(P^*wP)/\lambda_{\min}(P^*wP)$ , and it turns out that the weight function serves as a pre-conditioner. We remark that this measure is more closely studied in Subsection 4.2.

To illustrate the behavior of the weights with respect to this measure, in Table 1 we compute  $\text{cond}(P^*wP)$  for the weight functions arising from Choices 1 and 2 (cf. Subsection 2.2.2) with oversampling rate  $R = 8$ .

Table 1: Comparison of Choices 1 and 2 based on the performance measure  $\text{cond}(P^*wP)$ .

$N$	32	64	128	256	512
Choice 1	1.379	1.503	1.621	1.731	1.833
Choice 2	1.760	1.887	2.001	2.104	N/A

## 3 Digital Shearlet Transform using Compactly Supported Shearlets

In this section, we will discuss two implementation strategies for computing shearlet coefficients associated with a cone-adapted discrete shearlet system now based on *compactly supported* shearlets, as introduced in Chapter [1]. Again, one main focus will be on deriving a digitization which is faithful to the continuum setting.

Recall that in the context of wavelet theory, faithful digitization is achieved by the concept of multiresolution analysis, where scaling and translation are digitized by discrete operations: Downsampling, upsampling and convolution. In the case of directional transforms however, *three* types of operators: Scaling, translation and direction, need to be digitized. In this section, we will pay particular attention to deriving a framework in which each of the three operators is faithfully interpreted as a digitized operation in digital domain. Both approaches will be based on the following digitization strategies:

- Scaling and translation: A multiresolution analysis associated with anisotropic scaling  $A_{2^j}$  can be applied for each shear parameter  $k$ .

- **Directionality:** A faithful digitization of shear operator  $S_{2^{-j/2}k}$  has to be achieved with particular care.

After stating and discussing the two main obstacles we are facing when considering compactly supported shearlets in Subsection 3.1, we present the digital separable shearlet transform (DSST), which is associated with a shearlet system generated by a separable function alongside with discussions on its properties, e.g., its redundancy; see Subsection 3.2. Subsection 3.3 then presents the digital non-separable shearlet transform (DNST), whose shearlet elements are generated by non-separable shearlet generator.

### 3.1 Problems with Digitization of Compactly Supported Shearlets

Compactly supported shearlets have several advantages, and we exemplarily mention superior spatial localization and simplified boundary adaptation. However, we have to face the following two problems:

- (P1) Compactly supported shearlets do not form a tight frame, which prevents utilization of the adjoint as inverse transform.
- (P2) There does not exist a natural hierarchical structure, mainly due to the application of a shear matrix, which – unlike for the wavelet transform – does not allow a multiresolution analysis without destroying a faithful adaption of the continuum setting.

Let us now comment on these two obstacles, before delving into the details of the implementation in Subsection 3.2.

#### 3.1.1 Tightness

Let us first comment on the problem of non-tightness. Letting  $(\sigma_i)_{i \in I}$  denote a frame for  $L^2(\mathbb{R}^2)$  – for example, a shearlet frame –, each function  $f \in L^2(\mathbb{R}^2)$  can be reconstructed from its frame coefficients  $(\langle f, \sigma_i \rangle)_{i \in I}$  by

$$f = \sum_{i \in I} \langle f, \sigma_i \rangle S^{-1}(\sigma_i),$$

where  $S = \sum_{i \in I} \langle \cdot, \sigma_i \rangle \sigma_i$  is the associated frame operator on  $L^2(\mathbb{R}^2)$ , see Chapter [1]. However, in case that  $(\sigma_i)_{i \in I}$  does not form a *tight* frame, it is in general difficult to explicitly compute the dual frame elements  $S^{-1}(\sigma_i)$ .

Nevertheless, it is well known that the inverse frame operator  $S^{-1}$  can be effectively approximated using iterative schemes such as the Conjugate Gradient method provided that the frame  $(\sigma_i)_{i \in I}$  has ‘good’ frame bounds in the sense of their ratio being ‘close’ to 1, see also [24]. Therefore, now focussing on the situation of shearlet frames, we may argue that input data  $f$  can be efficiently reconstructed from its shearlet coefficients, if we use a compactly supported shearlet frame with ‘good’ frame bounds. In fact, the theoretical frame bounds of compactly supported shearlet frames have been theoretically estimated as well as numerically computed in [19]. These results were derived for the class of 2D separable shearlet generators  $\psi$  already described in Chapter [1], which we briefly recall for the convenience of the reader:

For positive integers  $K$  and  $L$  fixed, let the 1D lowpass filter  $m_0$  be defined by

$$|m_0(\xi_1)|^2 = (\cos(\pi\xi_1))^{2K} \sum_{n=0}^{L-1} \binom{K-1+n}{n} (\sin(\pi\xi_1))^{2n},$$

for  $\xi_1 \in \mathbb{R}$ . Further, define the associated bandpass filter  $m_1$  by

$$|m_1(\xi_1)|^2 = |m_0(\xi_1 + 1/2)|^2, \quad \xi_1 \in \mathbb{R},$$

and the 1D scaling function  $\phi_1$  by

$$\hat{\phi}_1(\xi_1) = \prod_{j=0}^{\infty} m_0(2^{-j}\xi_1), \quad \xi_1 \in \mathbb{R}.$$

Using the filter  $m_1$  and scaling function  $\phi_1$ , we now define the 2D scaling function  $\phi$  and separable shearlet generator  $\psi$  by

$$\hat{\phi}(\xi_1, \xi_2) = \hat{\phi}_1(\xi_1)\hat{\phi}_1(\xi_2) \quad \text{and} \quad \hat{\psi}(\xi_1, \xi_2) = m_1(4\xi_1)\hat{\phi}_1(\xi_1)\hat{\phi}_1(2\xi_2). \quad (3.1)$$

In [19], it was shown that compactly supported shearlets  $\psi_{j,k,m}$  generated by the shearlet generator  $\psi$  form a frame for  $L^2(C)^\vee$  with appropriately chosen parameters  $K$  and  $L$ , where

$$C = \{\xi \in \mathbb{R}^2 : |\xi_2/\xi_1| \leq 1, |\xi_1| \geq 1\}.$$

This construction is directly extended to construct a cone-adapted discrete shearlet frame for  $L^2(\mathbb{R}^2)$  (cf. also Chapters [1] and [4]).

Table 2 provides some numerically estimated frame bounds in  $L^2(C)$  for certain choice of  $K$  and  $L$ . It shows that indeed the ratio of the frame bounds of this class of compactly supported shearlet frames is sufficient small for utilizing an iterative scheme for efficient reconstruction; in this sense the frame bounds are 'good'.

Table 2: Numerically estimated frame bounds for various choices of the parameters  $K$  and  $L$ .  $c_1$  and  $c_2$  are the sampling constants in the sampling matrix  $M_c$  for translation (see Chapter [1]).

$K$	$L$	$c_1$	$c_2$	B/A
39	19	0.90	0.15	4.1084
39	19	0.90	0.20	4.1085
39	19	0.90	0.25	4.1104
39	19	0.90	0.30	4.1328
39	19	0.90	0.40	5.2495

The frequency covering by compactly supported shearlets  $\psi_{j,k,m}$ ,

$$|\hat{\phi}(\xi)|^2 + \sum_{j \geq 0} \sum_{k \in K_j} |\hat{\psi}(S_k^T A_{2^j} \xi)|^2 + |\hat{\psi}(\tilde{S}_k^T \tilde{A}_{2^j} \xi)|^2,$$

is closely related to the ratio of frames bounds and, in particular, which areas in frequency domain cause a larger ratio. This function is illustrated in Fig. 5, which shows that its upper and lower bounds are as expected well controlled.

### 3.1.2 Hierarchical Structure

Let us finally comment on the problem to achieve a hierarchical structuring. To allow fast implementations, the data structure of the transform is essential. The hierarchical structure of the wavelet transform associated with a multiresolution analysis, for instance, enables a fast implementation based on filterbanks. In addition, such a hierarchical ordering provides a full tree structure across scales, which is of particular importance for various applications such as image compression and adaptive PDE schemes. It is in fact mainly due to this property – and

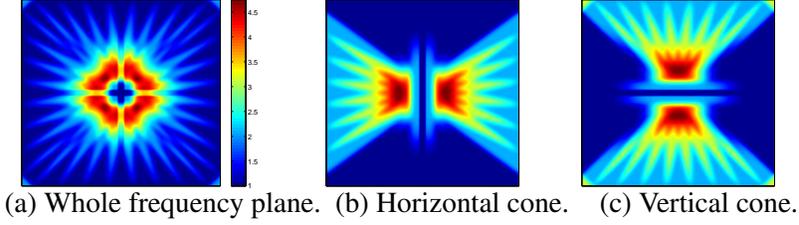


Figure 5: Frequency covering by shearlets  $|\hat{\psi}_{j,k,m}|^2$ : (a) Frequency covering of the entire frequency plane. (b) Frequency covering of the horizontal cone. (c) Frequency covering of the vertical cone.

the unified treatment of the continuum and digital setting – that the wavelet transform became an extremely successful methodology for many practical applications.

From a certain viewpoint, shearlets  $\psi_{j,k,m}$  can essentially be regarded as wavelets associated with an anisotropic scale matrix  $A_{2^j}$ , when the shear parameter  $k$  is fixed. This observation allows to apply the wavelet transform to compute the shearlet coefficients, once the shear operation is computed for each shear parameter  $k$ . This approach will be undertaken in the digital formulation of the compactly supported shearlet transform, and, in fact, this approach implements a hierarchical structure into the shearlet transform. The reader should note that this approach does not lead to a completely hierarchical structured shearlet transform – also compare our discussion at the beginning of this section –, but it will be sufficient for deriving a fast implementation while retaining a faithful digitization.

### 3.2 Digital Separable Shearlet Transform (DSST)

We now describe a faithful digitization of the continuum domain shearlet transform based on compactly supported shearlets as introduced in [22], which moreover is highly computationally efficient.

#### 3.2.1 Faithful Digitization of the Compactly Supported Shearlet Transform

We start by discussing those theoretical aspects which allow a faithful digitization of the shearlet transform associated with the shearlet system generated by (3.1). For this, we will only consider shearlets  $\psi_{j,k,m}$  for the horizontal cone, i.e., belonging to  $\Psi(\psi, c)$ . Notice that the same procedure can be applied to compute the shearlet coefficients for the vertical cone, i.e., those belonging to  $\tilde{\Psi}(\tilde{\psi}, c)$ , except for switching the order of variables.

To construct a separable shearlet generator  $\psi \in L^2(\mathbb{R}^2)$  and an associated scaling function  $\phi \in L^2(\mathbb{R}^2)$ , let  $\phi \in L^2(\mathbb{R})$  be a compactly supported 1D scaling function satisfying

$$\phi_1(x_1) = \sum_{n_1 \in \mathbb{Z}} h(n_1) \sqrt{2} \phi_1(2x_1 - n_1) \quad (3.2)$$

for some ‘appropriately chosen’ filter  $h$  – we comment on the required condition below. An associated compactly supported 1D wavelet  $\psi_1 \in L^2(\mathbb{R})$  can then be defined by

$$\psi_1(x_1) = \sum_{n_1 \in \mathbb{Z}} g(n_1) \sqrt{2} \phi_1(2x_1 - n_1), \quad (3.3)$$

where again  $g$  is an ‘appropriately chosen’ filter. The selected shearlet generator is then defined to be

$$\psi(x_1, x_2) = \psi_1(x_1) \phi_1(x_2), \quad (3.4)$$

and the scaling function by

$$\phi(x_1, x_2) = \phi_1(x_1)\phi_1(x_2).$$

Let us comment on whether this is indeed a special case of the shearlet generators defined in (3.1). The Fourier transform of  $\psi$  defined in (3.4) takes the form

$$\hat{\psi}(\xi_1, \xi_2) = m_1(\xi_1/2)\hat{\phi}_1(\xi_1/2)\hat{\phi}_1(\xi_2/2),$$

where  $m_1$  is a trigonometric polynomial whose Fourier coefficients are  $g(n_1)$ . We need to compare this expression with the Fourier transform of the shearlet generator  $\psi$  given in (3.1), which is

$$\hat{\psi}(\xi_1, \xi_2) = m_1(4\xi_1)\hat{\phi}_1(2\xi_1)\hat{\phi}_1(\xi_2),$$

with 1D scaling function  $\phi_1$  defined in (3.2). We remark that this later scaling function is slightly different defined as in (3.1). This small adaption is for the sake of presenting a simpler version of the implementation; essentially the same implementation strategy as the one we will describe can be applied to the shearlet generator given in (3.1).

The filter coefficients  $h$  and  $g$  are required to be chosen so that  $\psi$  satisfies a certain decay condition (cf. [19] of Chapter [1]) to guarantee a stable reconstruction from the shearlet coefficients.

For the signal  $f \in L^2(\mathbb{R}^2)$  to be analyzed, we now assume that, for  $J > 0$  fixed,  $f$  is of the form

$$f(x) = \sum_{n \in \mathbb{Z}^2} f_J(n) 2^J \phi(2^J x_1 - n_1, 2^J x_2 - n_2). \quad (3.5)$$

Let us mention that this is a very natural assumption for a digital implementation in the sense that the scaling coefficients can be viewed as sample values of  $f$  – in fact  $f_J(n) = f(2^{-J}n)$  with appropriately chosen  $\phi$ . Now aiming towards a faithful digitization of the shearlet coefficients  $\langle f, \psi_{j,k,m} \rangle$  for  $j = 0, \dots, J-1$ , we first observe that

$$\langle f, \psi_{j,k,m} \rangle = \langle f(S_{2^{-j/2}k}(\cdot)), \psi_{j,0,m}(\cdot) \rangle, \quad (3.6)$$

and, WLOG we will from now on assume that  $j/2$  is integer; otherwise either  $\lceil j/2 \rceil$  or  $\lfloor j/2 \rfloor$  would need to be taken. Our observation (3.6) shows us in fact precisely how to digitize the shearlet coefficients  $\langle f, \psi_{j,k,m} \rangle$ : By applying the discrete separable wavelet transform associated with the anisotropic sampling matrix  $A_{2^j}$  to the sheared version of the data  $f(S_{2^{-j/2}k}(\cdot))$ . This however requires – compare the assumed form of  $f$  given in (3.5) – that  $f(S_{2^{-j/2}k}(\cdot))$  is contained in the scaling space

$$V_J = \{2^J \phi(2^J \cdot - n_1, 2^J \cdot - n_2) : (n_1, n_2) \in \mathbb{Z}^2\}.$$

It is easy to see that, for instance, if the shear parameter  $2^{-j/2}k$  is non-integer, this is unfortunately not the case. The true reason for this failure is that the shear matrix  $S_{2^{-j/2}k}$  does *not* preserve the regular grid  $2^{-J}\mathbb{Z}^2$  in  $V_J$ , i.e.,

$$S_{2^{-j/2}k}(\mathbb{Z}^2) \neq \mathbb{Z}^2.$$

In order to resolve this issue, we consider the new scaling space  $V_{J+j/2,J}^k$  defined by

$$V_{J+j/2,J}^k = \{2^{J+4/j} \phi(S_k(2^{J+j/2} \cdot - n_1, 2^J \cdot - n_2)) : (n_1, n_2) \in \mathbb{Z}^2\}.$$

We remark that the scaling space  $V_{J+j/2,J}^k$  is obtained by refining the regular grid  $2^{-J}\mathbb{Z}^2$  along the  $x_1$ -axis by a factor of  $2^{j/2}$ . With this modification, the new grid  $2^{-J-j/2}\mathbb{Z} \times 2^{-J}\mathbb{Z}$  is now invariant under the shear operator  $S_{2^{-j/2}k}$ , since with  $Q = \text{diag}(2, 1)$ ,

$$\begin{aligned} 2^{-J-j/2}\mathbb{Z} \times 2^{-J}\mathbb{Z} &= 2^{-J}Q^{-j/2}(\mathbb{Z}^2) = 2^{-J}Q^{-j/2}(S_k(\mathbb{Z}^2)) \\ &= S_{2^{-j/2}k}(2^{-J-j/2}\mathbb{Z} \times 2^{-J}\mathbb{Z}). \end{aligned}$$

This allows us to rewrite  $f(S_{2^{-j/2}k}(\cdot))$  in (3.6) in the following way.

**Lemma 3.1.** *Retaining the notations and definitions from this subsection, letting  $\uparrow 2^{j/2}$  and  $*_1$  denote the 1D upsampling operator by a factor of  $2^{j/2}$  and the 1D convolution operator along the  $x_1$ -axis, respectively, and setting  $h_{j/2}(n_1)$  to be the Fourier coefficients of the trigonometric polynomial*

$$H_{j/2}(\xi_1) = \prod_{k=0}^{j/2-1} \sum_{n_1 \in \mathbb{Z}} h(n_1) e^{-2\pi i 2^k n_1 \xi_1}, \quad (3.7)$$

we obtain

$$f(S_{2^{-j/2}k}(x)) = \sum_{n \in \mathbb{Z}^2} \tilde{f}_J(S_k n) 2^{J+j/4} \phi_k(2^{J+j/2} x_1 - n_1, 2^J x_2 - n_2),$$

where

$$\tilde{f}_J(n) = ((f_J)_{\uparrow 2^{j/2}} *_1 h_{j/2})(n).$$

The proof of this lemma requires the following result, which follows from the cascade algorithm in the theory of wavelet.

**Proposition 3.1** ([22]). *Assume that  $\phi_1$  and  $\psi_1 \in L^2(\mathbb{R})$  satisfy equations (3.2) and (3.3) respectively. For positive integers  $j_1 \leq j_2$ , we then have*

$$2^{\frac{j_1}{2}} \phi_1(2^{j_1} x_1 - n_1) = \sum_{d_1 \in \mathbb{Z}} h_{j_2-j_1}(d_1 - 2^{j_2-j_1} n_1) 2^{\frac{j_2}{2}} \phi_1(2^{j_2} x_1 - d_1) \quad (3.8)$$

and

$$2^{\frac{j_1}{4}} \psi_1(2^{j_1} x_1 - n_1) = \sum_{d_1 \in \mathbb{Z}} g_{j_2-j_1}(d_1 - 2^{j_2-j_1} n_1) 2^{\frac{j_2}{2}} \phi_1(2^{j_2} x_1 - d_1), \quad (3.9)$$

where  $h_j$  and  $g_j$  are the Fourier coefficients of the trigonometric polynomials  $H_j$  defined in (3.7) and  $G_j$  defined by

$$G_j(\xi_1) = \left( \prod_{k=0}^{j-2} \sum_{n_1 \in \mathbb{Z}} h(n_1) e^{-2\pi i 2^k n_1 \xi_1} \right) \left( \sum_{n_1 \in \mathbb{Z}} g(n_1) e^{-2\pi i 2^{j-1} n_1 \xi_1} \right)$$

for  $j > 0$  fixed.

*Proof of Lemma 3.1.* Equation (3.8) with  $j_1 = J$  and  $j_2 = J + j/2$  implies that

$$2^{J/2} \phi_1(2^J x_1 - n_1) = \sum_{d_1 \in \mathbb{Z}} h_{J-j/2}(d_1 - 2^{j/2} n_1) 2^{J/2+j/4} \phi_1(2^{J+j/2} x_1 - d_1). \quad (3.10)$$

Also, since  $\phi$  is a 2D separable function of the form  $\phi(x_1, x_2) = \phi_1(x_1)\phi_1(x_2)$ , we have that

$$f(x) = \sum_{n_2 \in \mathbb{Z}} \left( \sum_{n_1 \in \mathbb{Z}} f_J(n_1, n_2) 2^{J/2} \phi_1(2^J x_1 - n_1) \right) 2^{J/2} \phi_1(2^J x_2 - n_2).$$

By (3.10), we obtain

$$f(x) = \sum_{n \in \mathbb{Z}^2} \tilde{f}_J(n) 2^{J+j/4} \phi(2^J Q^{j/2} x - n),$$

where  $Q = \text{diag}(2, 1)$ . Using  $Q^{j/2} S_{2^{-j/2}k} = S_k Q^{j/2}$ , this finally implies

$$\begin{aligned} f(S_{2^{-j/2}k}(x)) &= \sum_{n \in \mathbb{Z}^2} \tilde{f}_J(n) 2^{J+j/4} \phi(2^J Q^{j/2} S_{2^{-j/2}k}(x) - n) \\ &= \sum_{n \in \mathbb{Z}^2} \tilde{f}_J(n) 2^{J+j/4} \phi(S_k(2^J Q^{j/2} x - S_{-k} n)) \\ &= \sum_{n \in \mathbb{Z}^2} \tilde{f}_J(S_k n) 2^{J+j/4} \phi(S_k(2^J Q^{j/2} x - n)). \end{aligned}$$

The lemma is proved.  $\square$

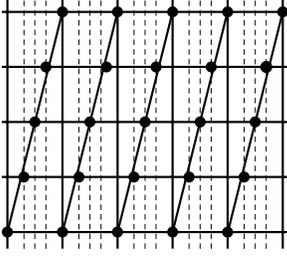


Figure 6: Illustration of application of the digital shear operator  $S_{-1/4}^d$ : The dashed lines correspond to the refinement of the integer grid. The new sample values lie on the intersections of the sheared lines associated with  $S_{1/4}$  with this refined grid.

The second term to be digitized in (3.6) is the shearlet  $\psi_{j,k,m}$  itself. A direct corollary from Proposition 3.1 is the following result.

**Lemma 3.2.** *Retaining the notations and definitions from this subsection, we obtain*

$$\psi_{j,k,m}(x) = \sum_{d \in \mathbb{Z}^2} g_{J-j}(d_1 - 2^{J-j}m_1)h_{J-j/2}(d_2 - 2^{J-j/2}m_2)2^{J+j/4}\phi(2^Jx - d).$$

As already indicated before, we will make use of the discrete separable wavelet transform associated with an anisotropic scaling matrix, which, for  $j_1$  and  $j_2 > 0$  as well as  $c \in \ell(\mathbb{Z}^2)$ , we define by

$$W_{j_1, j_2}(c)(n_1, n_2) = \sum_{m \in \mathbb{Z}^2} g_{j_1}(m_1 - 2^{j_1}n_1)h_{j_2}(m_2 - 2^{j_2}n_2)c(m_1, m_2), \quad (n_1, n_2) \in \mathbb{Z}^2. \quad (3.11)$$

Finally, Lemmata 3.1 and 3.2 yield the following digitizable form of the shearlet coefficients  $\langle f, \Psi_{j,k,m} \rangle$ .

**Theorem 3.1** ([22]). *Retaining the notations and definitions from this subsection, and letting  $\downarrow_{2^{j/2}}$  be 1D downsampling by a factor of  $2^{j/2}$  along the horizontal axis, we obtain*

$$\langle f, \Psi_{j,k,m} \rangle = W_{J-j, J-j/2} \left( \left( (\tilde{f}_J(S_k \cdot) * \Phi_k) *_1 \bar{h}_{j/2} \right) \downarrow_{2^{j/2}} \right) (m),$$

where  $\Phi_k(n) = \langle \phi(S_k(\cdot)), \phi(\cdot - n) \rangle$  for  $n \in \mathbb{Z}^2$ , and  $\bar{h}_{j/2}(n_1) = h_{j/2}(-n_1)$ .

### 3.2.2 Algorithmic Realization

Computing the shearlet coefficients using Theorem 3.1 now restricts to applying the discrete separable wavelet transform (3.11) associated with the sampling matrix  $A_{2^j}$  to the scaling coefficients

$$S_{2^{-j/2}k}^d(f_J)(n) := \left( (\tilde{f}_J(S_k \cdot) * \Phi_k) *_1 \bar{h}_{j/2} \right) \downarrow_{2^{j/2}}(n) \quad \text{for } f_J \in \ell^2(\mathbb{Z}^2). \quad (3.12)$$

Before we state the explicit steps necessary to achieve this, let us take a closer look at the scaling coefficients  $S_{2^{-j/2}k}^d(f_J)$ , which can be regarded as a new sampling of the data  $f_J$  on the integer grid  $\mathbb{Z}^2$  by the digital shear operator  $S_{2^{-j/2}k}^d$ . This procedure is illustrated in Fig. 6 in the case  $2^{-j/2}k = -1/4$ .

Let us also mention that the filter coefficients  $\Phi_k(n)$  in (3.12) can in fact be easily precomputed for each shear parameter  $k$ . For a practical implementation, one may sometimes even skip this additional convolution step assuming that  $\Phi_k = \chi_{(0,0)}$ .

Concluding, the implementation strategy for the DSST cascades the following steps:

- **Step 1:** For given input data  $f_J$ , apply the 1D upsampling operator by a factor of  $2^{j/2}$  at the finest scale  $j = J$ .
- **Step 2:** Apply 1D convolution to the upsampled input data  $f_J$  with 1D lowpass filter  $h_{j/2}$  at the finest scale  $j = J$ . This gives  $\tilde{f}_J$ .
- **Step 3:** Resample  $\tilde{f}_J$  to obtain  $\tilde{f}_J(S_k(n))$  according to the shear sampling matrix  $S_k$  at the finest scale  $j = J$ . Note that this resampling step is straightforward, since the integer grid is invariant under the shear matrix  $S_k$ .
- **Step 4:** Apply 1D convolution to  $\tilde{f}_J(S_k(n))$  with  $\bar{h}_{j/2}$  followed by 1D downsampling by a factor of  $2^{j/2}$  at the finest scale  $j = J$ .
- **Step 5:** Apply the separable wavelet transform  $W_{J-j, J-j/2}$  across scales  $j = 0, 1, \dots, J-1$ .

### 3.2.3 Digital Realization of Directionality

Since the digital realization of a shear matrix  $S_{2^{-j/2}k}$  by the digital shear operator  $S_{2^{-j/2}k}^d$  is crucial for deriving a faithful digitization of the continuum domain shearlet transform, we will devote this subsection to a closer analysis.

We start by remarking that in fact in the continuum domain, at least *two* operators exist which naturally provide directionality: Rotation and shearing. Rotation is a very convenient tool to provide directionality in the sense that it preserves important geometric information such as length, angles, and parallelism. However, this operator does not preserve the integer lattice, which causes severe problems for digitization. In contrast to this, a shear matrix  $S_k$  does not only provide directionality, but also preserves the integer lattice when the shear parameter  $k$  is integer. Thus, it is conceivable to assume that directionality can be naturally discretized by using a shear matrix  $S_k$ .

To start our analysis of the relation between a shear matrix  $S_{2^{-j/2}k}$  and the associated digital shear operator  $S_{2^{-j/2}k}^d$ , let us consider the following simple example: Set  $f_c = \chi_{\{x, x_1=0\}}$ . Then digitize  $f_c$  to obtain a function  $f_d$  defined on  $\mathbb{Z}^2$  by setting  $f_d(n) = f_c(n)$  for all  $n \in \mathbb{Z}^2$ . For fixed shear parameter  $s \in \mathbb{R}$ , apply the shear transform  $S_s$  to  $f_c$  yielding the sheared function  $f_c(S_s(\cdot))$ . Next, digitize also this function by considering  $f_c(S_s(\cdot))|_{\mathbb{Z}^2}$ . The functions  $f_d$  and  $f_c(S_s(\cdot))|_{\mathbb{Z}^2}$  are illustrated in Fig. 7 for  $s = -1/4$ . We now focus on the problem that the integer lattice is

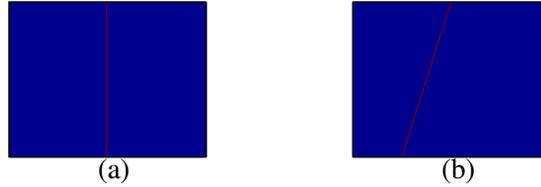


Figure 7: (a) Original image  $f_d(n)$ . (b) Sheared image  $f_c(S_{-1/4}n)$ .

not invariant under the shear matrix  $S_{1/4}$ . This prevents the sampling points  $S_{1/4}(n)$ ,  $n \in \mathbb{Z}^2$  from lying on the integer grid, which causes aliasing of the digitized image  $f_c(S_{-1/4}(\cdot))|_{\mathbb{Z}^2}$  as illustrated in Fig. 8(a). In order to avoid this aliasing effect, the grid needs to be refined by a factor of 4 along the horizontal axis followed by computing sample values on this refined grid.

More generally, when the shear parameter is given by  $s = -2^{-j/2}k$ , one can essentially avoid this directional aliasing effect by refining a grid by a factor of  $2^{j/2}$  along the horizontal axis followed by computing interpolated sample values on this refined grid. This ensures that the resulting grid contains the sampling points  $((2^{-j/2}k)n_2, n_2)$  for any  $n_2 \in \mathbb{Z}$  and is preserved

by the shear matrix  $S_{-2^{-j/2}k}$ . This procedure precisely coincides with the application of the digital shear operator  $S_{2^{-j/2}k}^d$ , i.e., we just described Steps 1 – 4 from Subsection 3.2.2 in which the new scaling coefficients  $S_{2^{-j/2}k}^d(f_J)(n)$  are computed.

Let us come back to the exemplary situation of  $f_c = \chi_{\{x: x_1=0\}}$  and  $S_{-1/4}$  we started our excursion with and compare  $f_c(S_{-1/4}(\cdot))|_{\mathbb{Z}^2}$  with  $S_{-1/4}^d(f_d)|_{\mathbb{Z}^2}$  obtained by applying the digital shear operator  $S_{-1/4}^d$  to  $f_d$ . And, in fact, the directional aliasing effect on the digitized image  $f_c(S_{-1/4}(n))$  in frequency illustrated in Fig. 8(a) is shown to be avoided in Fig. 8 (b)-(c) by considering  $S_{-1/4}^d(f_d)|_{\mathbb{Z}^2}$ . Thus application of the digital shear operator  $S_{2^{-j/2}k}^d$  allows a faithful

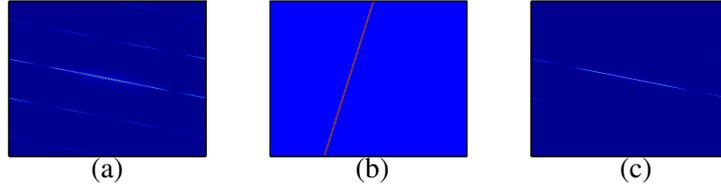


Figure 8: (a) Aliased image: DFT of  $f_c(S_{-1/4}(n))$ . (b) De-aliased image:  $S_{-1/4}^d(f_d)(n)$ . (c) De-aliased image: DFT of  $S_{-1/4}^d(f_d)(n)$ .

digitization of the shearing operator associated with the shear matrix  $S_{2^{-j/2}k}$ .

### 3.2.4 Redundancy

One of the main issues which practical applicability requires is controllable redundancy. To quantify the redundancy of the discrete shearlet transform, we assume that the input data  $f$  is a finite linear combination of translates of a 2D scaling function  $\phi$  at scale  $J$  as follows:

$$f(x) = \sum_{n_1=0}^{2^J-1} \sum_{n_2=0}^{2^J-1} d_n \phi(2^J x - n)$$

as it was already the hypothesis in (3.5). The redundancy – as we view it in our analysis – is then given by the number of shearlet elements necessary to represent  $f$ . Furthermore, to state the result in more generality, we allow an arbitrary sampling matrix  $M_c = \text{diag}(c_1, c_2)$  for translation, i.e., consider shearlet elements of the form

$$\psi_{j,k,m}(\cdot) = 2^{\frac{3}{2}j} \psi(S_k A_{2^j} \cdot -M_c m).$$

We then have the following result.

**Proposition 3.2** ([22]). *The redundancy of the DSST is*

$$\left(\frac{4}{3}\right) \left(\frac{1}{c_1 c_2}\right).$$

*Proof.* For this, we first consider shearlet elements for the horizontal cone for a fixed scale  $j \in \{0, \dots, J-1\}$ . We observe that there exist  $2^{j/2+1}$  shearing indices  $k$  and  $2^j \cdot 2^{j/2} \cdot (c_1 c_2)^{-1}$  translation indices associated with the scaling matrix  $A_{2^j}$  and the sampling matrix  $M_c$ , respectively. Thus,  $2^{2j+1} (c_1 c_2)^{-1}$  shearlet elements from the horizontal cone are required for representing  $f$ . Due to symmetry reasons, we require the same number of shearlet elements from

the vertical cone. Finally, about  $c_1^{-2}$  translates of the scaling function  $\phi$  are necessary at the coarsest scale  $j = 0$ .

Summarizing, the total number of necessary shearlet elements across all scales is about

$$\left(\frac{4}{c_1 c_2}\right) \left(\sum_{j=0}^{J-1} 2^{2j} + 1\right) = \left(\frac{4}{c_1 c_2}\right) \left(\frac{2^{2J} + 2}{3}\right)$$

The redundancy of each shearlet frame can now be computed as the ratio of the number of coefficients  $d_n$  and this number. Letting  $J \rightarrow \infty$  proves the claim.  $\square$   $\square$

As an example, choose a translation grid with parameters  $c_1 = 1$  and  $c_2 = 0.4$ . Then the associated DSST has asymptotic redundancy  $10/3$ .

### 3.2.5 Computational Complexity

A further essential characteristics is the computational complexity (see also Subsection 4.6), which we now formally compute for the discrete shearlet transform.

**Proposition 3.3** ([19]). *The computational complexity of the DSST is*

$$O(2^{\log_2(1/2(L/2-1))} L \cdot N).$$

*Proof.* Analyzing Steps 1 – 5 from Subsection 3.2.2, we observe that the most time consuming step is the computation of the scaling coefficients in Steps 1 – 4 for the finest scale  $j = J$ . This step requires 1D upsampling by a factor of  $2^{j/2}$  followed by 1D convolution for each direction associated with the shear parameter  $k$ . Letting  $L$  denote the total number of directions at the finest scale  $j = J$ , and  $N$  the size of 2D input data, the computational complexity for computing the scaling coefficients in Steps 1 – 4 is  $O(2^{j/2} L \cdot N)$ . The complexity of the discrete separable wavelet transform associated with  $A_{2^j}$  for Step 5 requires  $O(N)$  operations, wherefore it is negligible. The claim follows from the fact that  $L = 2(2 \cdot 2^{j/2} + 1)$ .  $\square$   $\square$

It should be noted that the total computational cost depends on the number  $L$  of shear parameters at the finest scale  $j = J$ , and this total cost grows approximately by a factor of  $L^2$  as  $L$  is increased. It should though be emphasized that  $L$  can be chosen in such a way that this shearlet transform is favorably comparable to other redundant directional transforms with respect to running time as well as performance. A reasonable number of directions at the finest scale is 6, in which case the constant factor  $2^{\log_2(1/2(L/2-1))}$  in Proposition 3.3 equals 1. Hence in this case the running time of this shearlet transform is only about 6 times slower than the discrete orthogonal wavelet transform, thereby remains in the range of the running time of other directional transforms.

### 3.2.6 Inverse DSST

In Subsection 3.1.1, we already discussed that this transform is not an isometry, wherefore the adjoint cannot be used as an inverse transform. However, the ‘good’ ratio of the frame bounds in the sense as detailed in Subsection 3.1.1 leads to a fast convergence rate of iterative methods such as the conjugate gradient method. Let us mention that using the conjugate gradient method basically requires computing the forward DSST and its adjoint, and we refer to [24] and also Subsection 2.4.2 for more details.

### 3.3 Digital Non-Separable Shearlet Transform (DNST)

In this section, we describe an alternative approach to derive a faithful digitization of a discrete shearlet transform associated with compactly supported shearlets. This algorithmic realization, which was developed in [23], resolves the following drawbacks of the DSST:

- Since this transform is not based on a tight frame, an additional computational effort is necessary to approximate the inverse of the shearlet transform by iterative methods.
- Computing the interpolated sampling values in (3.12) requires additional computational costs.
- This shearlet transform is not shift-variant, even when downsampling associated with  $A_{2^j}$  is omitted.

We emphasize that although this alternative approach resolves these problems, the algorithm DSST provides a much more faithful digitization in the sense that the shearlet coefficients can be exactly computed in this framework.

The main difference between DSST and DNST will be to exploit *non-separable* shearlet generators, which give more flexibility.

#### 3.3.1 Shearlet Generators

We start by introducing the *non-separable* shearlet generators utilized in DNST. First, define the shearlet generator  $\psi^{\text{non}}$  by

$$\hat{\psi}^{\text{non}}(\xi) = P(\xi_1, 2\xi_2)\hat{\psi}(\xi),$$

where the trigonometric polynomial  $P$  is a 2D fan filter (c.f. [12]). For an illustration of  $P$  we refer to Fig. 9(a). This in turn defines shearlets  $\psi_{j,k,m}^{\text{non}}$  generated by non-separable generator functions  $\psi_j^{\text{non}}$  for each scale index  $j \geq 0$  by setting

$$\psi_{j,k,m}^{\text{non}}(x) = 2^{\frac{3}{4}j}\psi^{\text{non}}(S_k A_{2^j} x - M_{c_j} m),$$

where  $M_{c_j}$  is a sampling matrix given by  $M_{c_j} = \text{diag}(c_1^j, c_2^j)$  and  $c_1^j$  and  $c_2^j$  are sampling constants for translation.

One major advantage of these shearlets  $\psi_{j,k,m}^{\text{non}}$  is the fact that a fan filter enables refinement of the directional selectivity in frequency domain at each scale. Fig. 9(a)-(b) show the refined essential support of  $\hat{\psi}_{j,k,m}^{\text{non}}$  as compared to shearlets  $\psi_{j,k,m}$  arising from a separable generator as in Subsection 3.2.1.

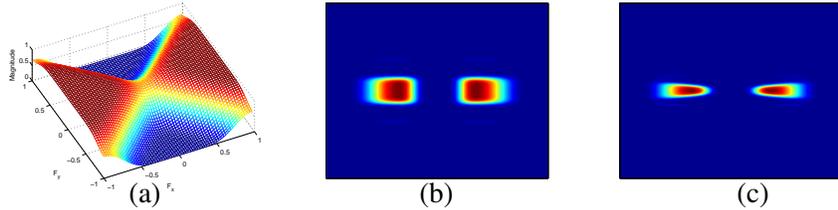


Figure 9: (a) Magnitude response of 2D fan filter. (b) Non-separable shearlet  $\psi_{j,k,m}^{\text{non}}$ . (c) Separable shearlet  $\psi_{j,k,m}$ .

### 3.3.2 Algorithmic Realization

Next, our aim is to derive a digital formulation of the shearlet coefficients  $\langle f, \psi_{j,k,m}^{\text{non}} \rangle$  for a function  $f$  as given in (3.5). We will only discuss the case of shearlet coefficients associated with  $A_{2^j}$  and  $S_k$ ; the same procedure can be applied for  $\tilde{A}_{2^j}$  and  $\tilde{S}_k$  except for switching the order of variables  $x_1$  and  $x_2$ .

In Subsection 3.2.3, we discretized a sheared function  $f(S_{2^{-j/2}k} \cdot)$  using the digital shear operator  $S_{2^{-j/2}k}^d$  as defined in (3.12). In this implementation, we walk a different path. We digitalize the shearlets  $\psi_{j,k,m}^{\text{non}}(\cdot) = \psi_{j,0,m}^{\text{non}}(S_{2^{-j/2}k} \cdot)$  by combining multiresolution analysis and digital shear operator  $S_{2^{-j/2}k}^d$  to digitize the wavelet  $\psi_{j,0,m}^{\text{non}}$  and the shear operator  $S_{2^{-j/2}k}$ , respectively. This yields digitized shearlet filters of the form

$$\psi_{j,k}^d(n) = S_{2^{-j/2}k}^d(p_{J-j/2} * w_j)(n),$$

where  $w_j$  is the 2D separable wavelet filter defined by  $w_j(n_1, n_2) = g_{J-j}(n_1) \cdot h_{J-j/2}(n_2)$  and  $p_{J-j/2}(n)$  are the Fourier coefficients of the 2D fan filter given by  $P(2^{J-j}\xi_1, 2^{J-j/2+1}\xi_2)$ . The DNST associated with the non-separable shearlet generators  $\psi_j^{\text{non}}$  is then given by

$$\text{DNST}_{j,k}(f_J)(n) = (f_J * \bar{\psi}_{j,k}^d)(2^{J-j}c_1^j n_1, 2^{J-j/2}c_2^j n_2), \quad \text{for } f_J \in \ell^2(\mathbb{Z}^2).$$

We remark that the discrete shearlet filters  $\psi_{j,k}^d$  are computed by using a similar ideas as in Subsection 3.2.1. As before, those filter coefficients can be precomputed to avoid additional computational effort.

Further notice that by setting  $c_1^j = 2^{j-J}$  and  $c_2^j = 2^{j/2-J}$ , the DNST simply becomes a 2D convolution. Thus, in this case, DNST is shear invariant.

### 3.3.3 Inverse DNST

In case that  $c_1^j = 2^{j-J}$  and  $c_2^j = 2^{j/2-J}$ , the dual shearlet filters  $\tilde{\psi}_{j,k}^d$  can be easily computed by,

$$\hat{\tilde{\psi}}_{j,k}^d(\xi) = \frac{\hat{\psi}_{j,k}^d(\xi)}{\sum_{j,k} |\hat{\psi}_{j,k}^d(\xi)|^2}$$

] and we obtain the reconstruction formula

$$f_J = \sum_{j,k} (f_J * \bar{\psi}_{j,k}^d) * \tilde{\psi}_{j,k}^d.$$

This reconstruction is stable due to the existence of positive upper and lower bounds of  $\sum_{j,k} |\hat{\tilde{\psi}}_{j,k}^d(\xi)|^2$ , which is implied by the frame property of nonseparable shearlets  $\psi_{j,k,m}^{\text{non}}$ , see [23]. Thus, no iterative methods are required for the inverse DNST. The frequency response of a discrete shearlet filter  $\psi_{j,k}^d$  and its dual  $\tilde{\psi}_{j,k}^d$  is illustrated in Fig. 10. We observe that primal and dual shearlet filters behave similarly in the sense that both of filters are very well localized in frequency.

## 4 Framework for Quantifying Performance

We next present the framework for quantifying performance of implementations of directional transforms, which was originally introduced in [20, 14]. This set of test measures was designed to analyze particular well-understood properties of a given algorithm, which in this case are the desiderata proposed at the beginning of this chapter. This framework was moreover introduced to serve as a tool for tuning the parameters of an algorithm in a rational way and as an objective

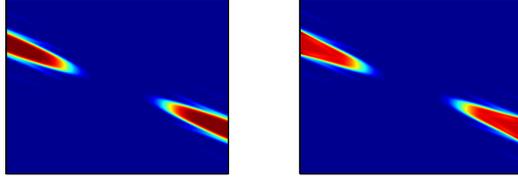


Figure 10: Magnitude response of shearlet filter  $\psi_{j,k}^d$  and its dual filter  $\tilde{\psi}_{j,k}^d$ .

common ground for comparison of different algorithms. The performance of the three algorithms FDST, DSST, and DNST will then be tested with respect to those measures. This will give us insight into their behavior with respect to the analyzed characteristics, and also allow a comparison. However, the test values of these three algorithms will also show the delicateness of designing such a testing framework in a fair manner, since due to the complexity of algorithmic realizations it is highly difficult to do each aspect of an algorithm justice. It should though be emphasized that – apart from being able to rationally tune parameters – such a framework of quantifying performance is essential for an objective judgement of algorithms. The codes of all measures are available in `ShearLab`.

In the following,  $S$  shall denote the transform under consideration,  $S^*$  its adjoint, and, if iterative reconstruction is tested,  $G_A J$  shall stand for the solution of the matrix problem  $AI = J$  using the conjugate gradient method with residual error set to be  $10^{-6}$ . Some measures apply specifically to transforms utilizing the pseudo-polar grid, for which purpose we introduce the notation  $P$  for the pseudo-polar Fourier transform,  $w$  shall denote the weighting applied to the values on the pseudo-polar grid, and  $W$  shall be the windowing with additional 2D iFFT.

#### 4.1 Algebraic Exactness

We require the transform to be the precise implementation of a theory for digital data on a pseudo-polar grid. In addition, to ensure numerical accuracy, we provide the following measure. This measure is designed for transforms utilizing the pseudo-polar grid.

**Measure 1.** *Generate a sequence of 5 (of course, one can choose any reasonable integer other than 5) random images  $I_1, \dots, I_5$  on a pseudo-polar grid for  $N = 512$  and  $R = 8$  with standard normally distributed entries. Our quality measure will then be the Monte Carlo estimate for the operator norm  $\|W^*W - Id\|_{op}$  given by*

$$M_{alg} = \max_{i=1, \dots, 5} \frac{\|W^*W I_i - I_i\|_2}{\|I_i\|_2}.$$

This measure applies to the FDST – not to the DSST or DNST –, for which we obtain

$$M_{alg} = 6.6E - 16.$$

This confirms that the windowing in the FDST is indeed up to machine precision a Parseval frame, which was already theoretically confirmed by Theorem 2.2.

#### 4.2 Isometry of Pseudo-Polar Transform

We next test the pseudo-polar transform itself which might be used in the algorithm under consideration. For this, we will provide three different measures, each being designed to test a different aspect.

**Measure 2.** • Closeness to isometry. Generate a sequence of 5 random images  $I_1, \dots, I_5$  of size  $512 \times 512$  with standard uniformly distributed entries. Our quality measure will then be the Monte Carlo estimate for the operator norm  $\|P^*wP - Id\|_{op}$  given by

$$M_{isom_1} = \max_{i=1, \dots, 5} \frac{\|P^*wPI_i - I_i\|_2}{\|I_i\|_2}.$$

- Quality of preconditioning. Our quality measure will be the spread of the eigenvalues of the Gram operator  $P^*wP$  given by

$$M_{isom_2} = \frac{\lambda_{\max}(P^*wP)}{\lambda_{\min}(P^*wP)}.$$

- Invertibility. Our quality measure will be the Monte Carlo estimate for the invertibility of the operator  $\sqrt{w}P$  using conjugate gradient method  $G_{\sqrt{w}P}$  (residual error is set to be  $10^{-6}$ , here  $G_{AJ}$  means solving matrix problem  $AI = J$  using conjugate gradient method) given by

$$M_{isom_3} = \max_{i=1, \dots, 5} \frac{\|G_{\sqrt{w}P}\sqrt{w}PI_i - I_i\|_2}{\|I_i\|_2}.$$

This measure applies to the FDST – not to the DSST or DNST –, for which we obtain the following numerical results, see Table 3.

Table 3: The numerical results for the test on isometry of the pseudo-polar transform.

	$M_{isom_1}$	$M_{isom_2}$	$M_{isom_3}$
FDST	9.3E-4	1.834	3.3E-7

The slight isometry deficiency of  $M_{isom_1} \approx 9.9E-4$  mainly results from the isometry deficiency of the weighting. However, for practical purposes this transform can be still considered to be an isometry allowing the utilization of the adjoint as inverse transform.

### 4.3 Parseval Frame Property

We now test the overall frame behavior of the system defined by the transform. These measures now apply to more than pseudo-polar based transforms, in particular, to FDST, DSST, and DNST.

**Measure 3.** Generate a sequence of 5 random images  $I_1, \dots, I_5$  of size  $512 \times 512$  with standard uniformly distributed entries. Our quality measure will then two-fold:

- Adjoint transform. The measure will be the Monte Carlo estimate for the operator norm  $\|S^*S - Id\|_{op}$  given by

$$M_{tight_1} = \max_{i=1, \dots, 5} \frac{\|S^*SI_i - I_i\|_2}{\|I_i\|_2}.$$

- Iterative reconstruction. Using conjugate gradient  $G_{\sqrt{w}P}$ , our measure will be given by

$$M_{tight_2} = \max_{i=1, \dots, 5} \frac{\|G_{\sqrt{w}P}W^*SI_i - I_i\|_2}{\|I_i\|_2}.$$

Table 4: The numerical results for the test on Parseval property.

	$M_{\text{tight}_1}$	$M_{\text{tight}_2}$
FDST	9.9E-4	3.8E-7
DSST	1.9920	1.2E-7
DNST	0.1829	5.8E-16 (with dual filters)

The following table, Table 4, presents the performance of FDST and DNST with respect to these quantitative measures.

The transform FDST is nearly tight as indicated by the measures  $M_{\text{tight}_1} = 9.9\text{E-}4$ , i.e., the chosen weights force the PPFT to be sufficiently close to an isometry for most practical purposes. If a higher accurate reconstruction is required,  $M_{\text{tight}_2} = 3.8\text{E-}7$  indicates that this can be achieved by the CG method. As expected,  $M_{\text{tight}_1} = 1.9920$  shows that DSST is not tight. Nevertheless, the CG method provides with  $M_{\text{tight}_2} = 1.2\text{E-}7$  a highly accurate approximation of its inverse. DNST is much closer to being tight than DSST (see  $M_{\text{tight}_1} = 0.1829$ ). We remark that this transform – as discussed – does not require the CG method for reconstruction. The value 5.8-16 was derived by using the dual shearlet filters, which show superior behavior.

#### 4.4 Space-Frequency-Localization

The next measure is designed to test the degree to which the analyzing elements, here phrased in terms of shearlets but can be extended to other analyzing elements, are space-frequency localized.

**Measure 4.** Let  $I$  be a shearlet in a  $512 \times 512$  image centered at the origin  $(257, 257)$  with slope 0 of scale 4, i.e.,  $\sigma_{4,0,0}^{11} + \sigma_{4,0,0}^{12}$ . Our quality measure will be four-fold:

- Decay in spatial domain. We compute the decay rates  $d_1, \dots, d_{512}$  along lines parallel to the y-axis starting from the line  $[257, :]$  and the decay rates  $d_{512}, \dots, d_{1024}$  with  $x$  and  $y$  interchanged. By decay rate, for instance, for the line  $[257 : 512, 1]$ , we first compute the smallest monotone majorant  $M(x, 1)$ ,  $x = 257, \dots, 512$  – note that we could also choose an average amplitude here or a different ‘envelope’ – for the curve  $|I(x, 1)|$ ,  $x = 257, \dots, 512$ . Then the decay rate is defined to be the average slope of the line, which is a least square fit to the curve  $\log(M(x, 1))$ ,  $x = 257, \dots, 512$ . Based on these decay rates, we choose our measure to be the average of the decay rates

$$M_{\text{decay}_1} = \frac{1}{1024} \sum_{i=1, \dots, 1024} d_i.$$

- Decay in frequency domain. Here we intend to check whether the Fourier transform of  $I$  is compactly supported and also the decay. For this, let  $\hat{I}$  be the 2D-FFT of  $I$  and compute the decay rates  $d_i$ ,  $i = 1, \dots, 1024$  as before. Then we define the following two measures:
  - Compactly supportedness.

$$M_{\text{supp}} = \frac{\max_{|u|, |v| \leq 3} |\hat{I}(u, v)|}{\max_{u, v} |\hat{I}(u, v)|}.$$

- Decay rate.

$$M_{\text{decay}_2} = \frac{1}{1024} \sum_{i=1, \dots, 512} d_i.$$

- Smoothness in spatial domain. We will measure smoothness by the average of local Hölder regularity. For each  $(u_0, v_0)$ , we compute  $M(u, v) = |I(u, v) - I(u_0, v_0)|$ ,  $0 < \max\{|u - u_0|, |v - v_0|\} \leq 4$ . Then the local Hölder regularity  $\alpha_{u_0, v_0}$  is the least square fit to the curve  $\log(|M(u, v)|)$ . Then our smoothness measure is given by

$$M_{smooth_1} = \frac{1}{512^2} \sum_{u,v} \alpha_{u,v}.$$

- Smoothness in frequency domain. We compute the smoothness now for  $\hat{I}$ , the 2D-FFT of  $I$  to obtain the new  $\alpha_{u,v}$  and define our measure to be

$$M_{smooth_2} = \frac{1}{512^2} \sum_{u,v} \alpha_{u,v}.$$

Let us now analyze the space-frequency localization of the shearlets utilized in FDST, DSST and DNST by these measures. The numerical results are presented in Table 5.

Table 5: The numerical results for the test on space-frequency localization.

	$M_{decay_1}$	$M_{supp}$	$M_{decay_2}$	$M_{smooth_1}$	$M_{smooth_2}$
FDST	-1.920	5.5E-5	-3.257	1.319	0.734
DSST	$-\infty$	8.6E-3	-1.195	0.012	0.954
DNST	$-\infty$	2.0E-3	-0.716	0.188	0.949

The shearlet elements associated with FDST are band-limited and those associated with DSST and DNST are compactly supported, which is clearly indicated by the values derived for  $M_{decay_1}$ ,  $M_{supp}$ , and  $M_{decay_2}$ . It would be expected that  $M_{decay_2} = -\infty$  for FDST due to the band-limitedness of the associated shearlets. The shearlet elements are however defined by their Fourier transform on a pseudo-polar grid, whereas the measure  $M_{decay_2}$  is taken after applying the 2D-FFT to the shearlets resulting in data on a cartesian grid, in particular, yielding a non-precisely compactly supported function.

The test values for  $M_{smooth_1}$  and  $M_{smooth_2}$  show that the associated shearlets are more smooth in spatial domain for FDST than for DSST and DNST, with the reversed situation in frequency domain.

## 4.5 Shear Invariance

Shearing naturally occurs in digital imaging, and it can – in contrast to rotation – be precisely realized in the digital domain. Moreover, for the shearlet transform, shear invariance can be proven and the theory implies

$$\left\langle 2^{3j/2} \psi(S_k^{-1} A_4^j \cdot -m), f(S_s \cdot) \right\rangle = \left\langle 2^{3j/2} \psi(S_{k+2^j s}^{-1} A_4^j \cdot -m), f \right\rangle.$$

We therefore expect to see this or a to the specific directional transform adapted behavior. The degree to which this goal is reached is tested by the following measure.

**Measure 5.** Let  $I$  be an  $256 \times 256$  image with an edge through the origin  $(129, 129)$  of slope 0. Given  $-1 \leq s \leq 1$ , generates an image  $I_s := I(S_s \cdot)$  and let  $S_j$  be the set of all possible scales

$j$  such that  $2^j s \in \mathbb{Z}$ . Our quality measure will then be the curve

$$M_{shear,j} = \max_{-2^j < k, k+2^j s < 2^j} \frac{\|C_{j,k}(SI_s) - C_{j,k+2^j s}(SI)\|_2}{\|I\|_2}, \quad \text{scale } j \in S_j,$$

where  $C_{j,k}$  is the shearlet coefficients at scale  $j$  and shear  $k$ .

We present our results in Table 6.

Table 6: The numerical results for the test on shear invariance.

	$M_{shear,1}$	$M_{shear,2}$	$M_{shear,3}$	$M_{shear,4}$
FDST	1.6E-5	1.8E-4	0.002	0.003

This table shows that the FDST is indeed almost shear invariant. A closer inspection shows that  $M_{shear,1}$  and  $M_{shear,2}$  are relatively small compared to the measurements with respect to finer scales  $M_{shear,3}$  and  $M_{shear,4}$ . The reason for this is the aliasing effect which shifts some energy to the high frequency part near the boundary away from the edge in the frequency domain.

We did not test DSST and DNST with respect to this measure, since these transforms show a different – not included in this Measure 5 – type of shear invariance behavior.

## 4.6 Speed

Speed is one of the most fundamental properties of each algorithm to analyze. Here, we test the speed up to a size of  $N = 512$  which regard as sufficient to computing the complexity.

**Measure 6.** Generate a sequence of 5 random images  $I_i$ ,  $i = 5, \dots, 9$  of size  $2^i \times 2^i$  with standard normally distributed entries. Let  $s_i$  be the speed of the shearlet transform  $S$  applied to  $I_i$ . Our hypothesis is that the speed behaves like  $s_i = c \cdot (2^{2i})^d$ ,  $2^{2i}$  being the size of the input. Let now  $\tilde{d}_a$  be the average slope of the line, which is a least square fit to the curve  $i \mapsto \log(s_i)$ . Let also  $f_i$  be the 2fft applied to  $I_i$ ,  $i = 5, \dots, 9$ . Our quality measure will then be three-fold:

- Complexity.

$$M_{speed_1} = \frac{\tilde{d}_a}{2 \log 2}.$$

- The Constant.

$$M_{speed_2} = \frac{1}{5} \sum_{i=5}^9 \frac{s_i}{(2^{2i})^{M_{speed,1}}}.$$

- Comparison with 2D-FFT.

$$M_{speed_3} = \frac{1}{5} \sum_{i=5}^9 \frac{s_i}{f_i}.$$

Table 7 presents the results of testing FDST, DSST and DNST with respect to these speed measures.

To interpret these results correctly, we remark that the DNST was tested only with test images  $I_i$  for  $i = 7, \dots, 9$ , since it can not be implemented for small size images. Interestingly, the results also show that the 2D FFT based convolution makes DNST comparable to DSST with respect to these speed measures, although it is much more redundant than DSST. Finally, the results show that FDST is comparable with both DSST and DNST with respect to complexity

Table 7: The numerical results for the test on speed.

	$M_{speed_1}$	$M_{speed_2}$	$M_{speed_3}$
FDST	1.156	9.3E-6	280.560
DSST	0.821	4.5E-3	88.700
DNST	1.081	9.9E-8	40.519

measure  $M_{speed_1}$ . From this, it is conceivable to assume that FDST is highly comparable with respect to speed for large scale computations. The larger value  $M_{speed_3} = 280.560$  appears due to the fact that the FDST employs fractional Fourier transforms on an oversampled pseudo-polar grid of size.

#### 4.7 Geometric Exactness

One major advantage of directional transforms is their sensitivity with respect to geometric features alongside with their ability to sparsely approximate those (cf. Chapter [4]). This measure is designed to analyze this property.

**Measure 7.** Let  $I_1, \dots, I_8$  be  $256 \times 256$  images of an edge through the origin  $(129, 129)$  and of slope  $[-1, -0.5, 0, 0.5, 1]$  and the transpose of the middle three, and let  $c_{i,j}$  be the associated shearlet coefficients for image  $I_i$  and scale  $j$ . Our quality measure will two-fold:

- Decay of significant coefficients. Consider the curve

$$\frac{1}{8} \sum_{i=1}^8 \max |c_{i,j}(\text{of analyzing elements aligned with the line})|, \quad \text{scale } j,$$

let  $d$  be the average slope of the line, which is a least square fit to log of this curve, and define

$$M_{geo_1} = d.$$

- Decay of insignificant coefficients. Consider the curve

$$\frac{1}{8} \sum_{i=1}^8 \max |c_{i,j}(\text{of all other analyzing elements})|, \quad \text{scale } j,$$

let  $d$  be the average slope of the line, which is a least square fit to log of this curve, and define

$$M_{geo_2} = d.$$

Table 8 shows the numerical test results for FDST, DSST, and DNST.

As expected, the decay rate of the insignificant shearlet coefficients of FDST, i.e., the ones not aligned with the line singularity, measured by  $M_{geo_2} \approx -2.032$  is much larger than the decay rate of the significant shearlet coefficients measured by  $M_{geo_1} \approx -1.358$ . Notice that this difference is even more significant in the case of the DSST and DNST.

#### 4.8 Stability

To analyze stability of an algorithm, we choose thresholding as the most common impact on a sequence of transform coefficients.

Table 8: The numerical results for the test on geometric exactness.

	$M_{geo_1}$	$M_{geo_2}$
FDST	-1.358	-2.032
DSST	-0.002	-0.030
DNST	-0.019	-0.342

**Measure 8.** Let  $I$  be the regular sampling of a Gaussian function with mean 0 and variance 256 on  $\{-128, 127\}^2$  generating an  $256 \times 256$ -image.

- Thresholding 1. Our first quality measure will be the curve

$$M_{thres_{1,p_1}} = \frac{\|G_{\sqrt{w}P}W^* thres_{1,p_1} SI - I\|_2}{\|I\|_2},$$

where  $thres_{1,p_1}$  discards  $100 \cdot (1 - 2^{-p_1})$  percent of the coefficients ( $p_1 = [2 : 2 : 10]$ ).

- Thresholding 2. Our second quality measure will be the curve

$$M_{thres_{2,p_2}} = \frac{\|G_{\sqrt{w}P}W^* thres_{2,p_2} SI - I\|_2}{\|I\|_2},$$

where  $thres_{2,p_2}$  sets all those coefficients to zero with absolute values below the threshold  $m(1 - 2^{-p_2})$  with  $m$  being the maximal absolute value of all coefficients. ( $p_2 = [0.001 : 0.01 : 0.041]$ )

Table 9 shows that even if we discard  $100(1 - 2^{-10}) \sim 99.9\%$  of the FDST coefficients, the original image is still well approximated by the reconstructed image. Thus the number of the significant coefficients is relatively small compared to the total number of shearlet coefficients. From Table 10, we note that knowledge of the shearlet coefficients with absolute value greater than  $m(1 - 1/2^{0.001}) (\sim 0.1\%$  of coefficients) is sufficient for precise reconstruction.

DNST shows a similar behavior with worse values for relatively large  $p_1$ . It should be however emphasized that firstly, the redundancy of DNST used in this test is 25 and this is lower than the redundancy of FDST, which is about 71. This effect can be more strongly seen by the test results of DSST whose redundancy with 4 even much smaller. Secondly, a significant part of the low frequency coefficients in both DSST and DNST will be removed by a relatively large threshold, since the ratio between the number of the low frequency coefficients and the total number of coefficients is much higher than FDST. This prohibits a similarly good reconstruction of a Gaussian function.

This test in particular shows the delicateness of comparing different algorithms by merely looking at the test values without a rational interpretation; in this case, without considering the redundancy and the ratio between the number of the low frequency coefficients and the total number of coefficients.

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Table 9: The numerical results for  $M_{thres_1, p_1}$ .

$p_1$	2	4	6	8	10
FDST	1.5E-08	7.2E-08	2.5E-05	0.001	0.007
DSST	0.02961	0.02961	0.02961	0.0296	0.0331
DNST	5.2E-10	1.2E-04	0.00391	0.0124	0.0396
DNST+DWT	1.2E-09	3.2E-06	3.4E-05	5.5E-05	5.5E-05

Table 10: The numerical results for  $M_{thres_2, p_2}$ .

$p_2$	0.001	0.011	0.021	0.031	0.041
FDST	0.005	0.039	0.078	0.113	0.154
DSST	0.030	0.036	0.046	0.056	0.072
DNST	0.002	0.018	0.035	0.055	0.076
DNST+DWT	0.001	0.013	0.020	0.024	0.031

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