

Preconditioning of Frames

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ABSTRACT

The recently introduced and characterized scalable frames can be considered as those frames which allow for perfect preconditioning in the sense that the frame vectors can be rescaled to yield a tight frame. In this paper we define m -scalability, a refinement of scalability based on the number of non-zero weights used in the rescaling process. We enlighten a close connection between this notion and elements from convex geometry. Another focus lies in the topology of scalable frames. In particular, we prove that the set of scalable frames with “usual” redundancy is nowhere dense in the set of frames.

Keywords: Scalable frames, tight frames, preconditioning

1. INTRODUCTION

Frame theory, both in the finite and infinite dimensional setting, has become a standard tool in mathematical signal processing and engineering. The main reason for this and, simultaneously, the key feature of frames is their redundancy which ensures their robustness against perturbations such as noise or erasures [d92,ck03]. For a detailed treatment of frames in theory and applications we refer the interested reader to [7, 9, 15, 16].

In this paper we consider frames for finite-dimensional real Euclidean spaces \mathbb{R}^N . In this context, a frame is a set $\Phi = \{\varphi_k\}_{k=1}^M \subset \mathbb{R}^N$, $M \geq N$, for which there exist positive constants A and B such that

$$A\|x\|^2 \leq \sum_{k=1}^M |\langle x, \varphi_k \rangle|^2 \leq B\|x\|^2 \quad (1)$$

holds for all $x \in \mathbb{R}^N$. Constants A and B as in (1) are called *frame bounds* of Φ . The frame Φ is called *tight* if $A = B$ is possible in (1). In this case we have $A = \frac{1}{N} \sum_{k=1}^M \|\varphi_k\|^2$. A tight frame with $A = B = 1$ in (1) is called *Parseval frame* (see, e.g., [2, 5]).

We will sometimes identify a frame $\Phi = \{\varphi_k\}_{k=1}^M \subset \mathbb{R}^N$ with the $N \times M$ matrix whose k th column is the vector φ_k . This matrix is called the *synthesis operator* of the frame. The adjoint Φ^T of Φ is called the *analysis operator*. Using the analysis operator, the relation (1) reads

$$A\|x\|^2 \leq \|\Phi^T x\|^2 \leq B\|x\|^2.$$

Hence, a frame Φ is tight if and only if some multiple of Φ^T is an isometry. Formulated in the language of numerical linear algebra, a tight frame is perfectly conditioned since the condition number of its analysis operator is one. It is therefore obvious that tight frames are highly advantageous over non-tight frames when applied to real world problems. It is thus desirable to construct tight frames by modifying frames in a very simple manner.

Recently, together with E.K. Tuley the authors introduced in [17] the so-called *scalable frames* (see also [18]). Hereby, a frame $\Phi = \{\varphi_k\}_{k=1}^M$ is *scalable* if the frame vectors φ_k , $k = 1, \dots, M$, can be rescaled such that the

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resulting frame is tight. Since the analysis operator after rescaling has the form $D\Phi^T$ with a diagonal matrix D , a scalable frame is a frame whose analysis operator allows for perfect pre-conditioning (see [1, 8, 14]), meaning that $D\Phi^T$ has condition number one. One of the main results in [17, 18] is a simple geometric characterization of the complement of the set of scalable frames in the set of all frames with a fixed number of frame vectors.

After the appearance of [17], scalable frames have also been investigated in the papers [10] and [4]. In [10] the authors analyzed the problem by making use of the properties of so-called diagram vectors [13] whereas [4] gives a detailed insight into the set of weights which can be used for scaling.

In the present paper we refine the definition of scalability by calling a (scalable) frame m -scalable if at most m non-zero weights can be used for the scaling.

Subsequently, this refinement leads to a reformulation of the scalability question in terms of the properties of certain polytopes associated to a nonlinear transformation of the frame vectors. This nonlinear transformation is related but not equivalent to the diagram vectors used in the results obtained in [10]. Using this reformulation, we establish new characterizations of scalable frames, based on one of the many versions of Farkas' Lemma and further illustrate the link between scalable frames and properties of convex polytopes. Finally, we investigate the topological properties of the set of scalable frames. In particular, we prove that in the set of frames in \mathbb{R}^N with M frame vectors the set of scalable frames is nowhere dense if $M < N(N+1)/2$. We wish to point out that the proofs of the results stated below can be found in [19].

2. PRELIMINARIES

First of all, let us fix some notation. If X is any set whose elements are indexed x_j , $j \in J$, and $I \subset J$, we define $X_I := \{x_i : i \in I\}$. Moreover, for the set $\{1, \dots, n\}$, $n \in \mathbb{N}$, we write $[n]$. The set of frames for \mathbb{R}^N with M elements will be denoted by $\mathcal{F}(M, N)$. We say that a frame $\Phi \in \mathcal{F}(M, N)$ is *degenerate* if one of its frame vectors is the zero-vector. If $\mathcal{X}(M, N)$ is a set of frames in $\mathcal{F}(M, N)$, we denote by $\mathcal{X}^*(M, N)$ the set of the non-degenerate frames in $\mathcal{X}(M, N)$. For example, $\mathcal{F}^*(M, N)$ is the set of non-degenerate frames in $\mathcal{F}(M, N)$.

We begin by recalling the following definition from [17, Definition 2.1].

DEFINITION 2.1. *A frame $\Phi = \{\varphi_k\}_{k=1}^M$ for \mathbb{R}^N is called scalable, respectively, strictly scalable, if there exist nonnegative, respectively, positive, scalars $c_1, \dots, c_M \in \mathbb{R}$ such that $\{c_k \varphi_k\}_{k=1}^M$ is a tight frame for \mathbb{R}^N . The set of scalable, respectively, strictly scalable, frames in $\mathcal{F}(M, N)$ is denoted by $\mathcal{SC}(M, N)$, respectively, $\mathcal{SC}_+(M, N)$.*

We now refine this definition in order to gain a better understanding of the structure of scalable frames.

DEFINITION 2.2. *Let $M, N, m \in \mathbb{N}$ be given such that $N \leq m \leq M$. A frame $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}(M, N)$ is said to be m -scalable, respectively, strictly m -scalable, if there exists a subset $I \subseteq [M]$, $\#I = m$, such that Φ_I is a scalable frame, respectively, a strictly scalable frame for \mathbb{R}^N . We denote the set of m -scalable frames, respectively, strictly m -scalable frames in $\mathcal{F}(M, N)$ by $\mathcal{SC}(M, N, m)$, respectively, $\mathcal{SC}_+(M, N, m)$.*

It is easily seen that for $m \leq m'$ we have that $\mathcal{SC}(M, N, m) \subset \mathcal{SC}(M, N, m')$. Therefore,

$$\mathcal{SC}(M, N) = \mathcal{SC}(M, N, M) = \bigcup_{m=N}^M \mathcal{SC}(M, N, m).$$

We often only write \mathcal{F} , \mathcal{SC} , \mathcal{SC}_+ , $\mathcal{SC}(m)$, and $\mathcal{SC}_+(m)$ instead of $\mathcal{SC}(M, N)$, $\mathcal{SC}_+(M, N)$, $\mathcal{SC}(M, N, m)$, and $\mathcal{SC}_+(M, N, m)$, respectively. The notations \mathcal{F}^* , \mathcal{SC}^* , \mathcal{SC}_+^* , $\mathcal{SC}(m)^*$, and $\mathcal{SC}_+(m)^*$ are to be read analogously.

Note that for a frame $\Phi \in \mathcal{F}$ to be m -scalable it is necessary that $m \geq N$, and given $M \geq N \geq 2$, if $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{SC}(M, N)$, then $\Phi \in \mathcal{SC}(m)$ for some $N \leq m \leq M$. In addition, $\Phi \in \mathcal{SC}(M, N)$ holds if and only if $T(\Phi) \in \mathcal{SC}(M, N)$ for one (and hence for all) orthogonal transformation(s) T on \mathbb{R}^N ; cf. [17, Corollary 2.6].

If $M \geq N$, we have $\Phi \in \mathcal{SC}(M, N, N)$ if and only if Φ contains an orthogonal basis of \mathbb{R}^N . This completely characterizes the set of N -scalable frames of $M \geq N$ vectors in \mathbb{R}^N . For frames with $M = N + 1$ vectors in \mathbb{R}^N we have the following result:

PROPOSITION 2.3. Let $N \geq 2$ and $\Phi = \{\varphi_k\}_{k=1}^{N+1} \in \mathcal{F}^*$ with $\varphi_k \neq \pm\varphi_\ell$ for $k \neq \ell$. If $\Phi \in \mathcal{SC}_+(N+1, N, N)$ then $\Phi \notin \mathcal{SC}_+(N+1, N, N+1)$. In particular,

$$\mathcal{SC}_+(N+1, N, N+1) \cap \mathcal{SC}_+(N+1, N, N) = \emptyset.$$

We conclude this section with the following remark:

REMARK 2.4. To determine that a frame Φ is scalable, we could always assume without loss of generality that all the frame vectors are in the upper-half plane, that is $\Phi \subset \mathbb{R}^{N-1} \times \mathbb{R}_{+,0}$ where $\mathbb{R}_{+,0} = [0, \infty)$. Indeed, given a frame $\Phi \subset \mathbb{R}^N$, assume that $\Phi = \Phi_1 \cup \Phi_2$ where

$$\Phi_1 = \{\varphi_k^{(1)} \in \Phi : \varphi_k^{(1)}(N) \geq 0\}$$

and

$$\Phi_2 = \{\varphi_k^{(2)} \in \Phi : \varphi_k^{(2)}(N) < 0\}.$$

Then the frame $\Phi' = \Phi_1 \cup (-\Phi_2) = \{\varphi_k^{(1)}\} \cup \{-\varphi_k^{(2)}\}$ has the same frame operator as Φ . In particular, if one is a tight frame so is the other. In addition, Φ is scalable if and only if Φ' is scalable with exactly the same set of weights.

3. SCALABLE FRAMES AND CONVEX POLYTOPES

Our characterizations of m -scalable frames will be stated in terms of certain convex polytopes and more generally using tools from convex geometry. Therefore, we collect below some key facts and properties needed to state and prove our results, and we refer to [3, 12, 20–22] for details.

3.1 Background on Convex Geometry

Let $X = \{x_i\}_{i=1}^M$ be a finite set in a real linear space E . The *convex hull generated by X* is the compact convex subset of E defined by

$$\text{co}(X) := \left\{ \sum_{i=1}^M \alpha_i x_i : \alpha_i \geq 0, \sum_{i=1}^M \alpha_i = 1 \right\}.$$

The *affine hull generated by X* is defined by

$$\text{aff}(X) := \left\{ \sum_{i=1}^M \alpha_i x_i : \sum_{i=1}^M \alpha_i = 1 \right\}.$$

Hence, we have $\text{co}(X) \subset \text{aff}(X)$. Recall that for fixed $a \in \text{aff}(X)$, the set

$$V(X) := \text{aff}(X) - a = \{y - a : y \in \text{aff}(X)\}$$

is a subspace of E (which is independent of $a \in \text{aff}(X)$) and that one defines

$$\dim X := \dim \text{co}(X) := \dim \text{aff}(X) := \dim V(X).$$

We shall use Carathéodory's Theorem for convex polytopes [21, Theorem 2.2.12], in deciding whether a frame is scalable:

THEOREM 3.1 (CARATHÉODORY). Let $X = \{x_1, \dots, x_k\}$ be a finite subset of E with $d := \dim X$. Then for each $x \in \text{co}(X)$ there exists $I \subset [k]$ with $\#I = d + 1$ such that $x \in \text{co}(X_I)$.

The *relative interior* of the polytope $\text{co}(X)$ denoted by $\text{ri co}(X)$, is the interior of $\text{co}(X)$ in the topology induced by $\text{aff}(X)$. It is true that $\text{ri co}(X) \neq \emptyset$ as long as $\#X \geq 2$; cf. [21, Lemma 3.2.8]. Furthermore,

$$\text{ri co}(X) := \left\{ \sum_{i=1}^M \lambda_i x_i : \lambda_i > 0, \sum_{i=1}^M \lambda_i = 1 \right\},$$

see [22, Theorem 2.3.7]. Moreover, the interior of $\text{co}(X)$ in E is non-empty if and only if $\text{aff}(X) = E$.

The following lemma characterizes $\dim X$ in terms of $\dim \text{span } X$.

LEMMA 3.2. *Let X be a finite set of points in E . Put $m := \dim \text{span } X$. Then $\dim X \in \{m - 1, m\}$. Moreover, the following statements are equivalent:*

- (i) $\dim X = m - 1$.
- (ii) For all linearly independent $X' \subset X$ with $\dim \text{span } X' = m$ we have $X \setminus X' \subset \text{aff}(X')$.
- (iii) For some linearly independent $X' \subset X$ with $\dim \text{span } X' = m$ we have $X \setminus X' \subset \text{aff}(X')$.

In the sequel we shall use a special case of Lemma 3.2, where X is a set of rank-one orthogonal projections. More specifically,

COROLLARY 3.3. *If the set X in Lemma 3.2 consists of rank-one orthogonal projections acting on a real Hilbert space, then we have*

$$\dim X = \dim \text{span } X - 1.$$

3.2 Scalability in Terms of Convex Combinations of Rank-One Matrices

For a frame $\Phi = \{\varphi_i\}_{i=1}^M$ in $\mathcal{F}(M, N)$ we set $X_\Phi := \{\varphi_i \varphi_i^T : i \in [M]\}$. This is a subset of S_N , the space of all real symmetric $N \times N$ -matrices. We shall also denote the set of positive multiples of the identity by $\mathbf{I}_+ := \{t \text{Id}_N : t > 0\}$. The following result is proved in [19].

PROPOSITION 3.4. *For a frame $\Phi \in \mathcal{F}(M, N)$ the following statements are equivalent:*

- (i) Φ is scalable, respectively, strictly scalable.
- (ii) $\mathbf{I}_+ \cap \text{co}(X_\Phi) \neq \emptyset$, respectively, $\mathbf{I}_+ \cap \text{ri co}(X_\Phi) \neq \emptyset$.

As pointed out earlier, for $m \leq m'$, $\mathcal{SC}(m) \subset \mathcal{SC}(m')$. The next result shows that given $\Phi \in \mathcal{SC}(M, N)$, there is a generic $N \leq m := m_\Phi \leq M$ such that $\Phi \in \mathcal{SC}(m)$.

PROPOSITION 3.5. *A frame $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}$ is scalable if and only if it is m -scalable, where $m := \dim \text{span } X_\Phi$.*

As $X_\Phi \subset S_N$ and $\dim S_N = N(N + 1)/2$, we immediately obtain the following corollary.

COROLLARY 3.6. *For $M \geq N(N + 1)/2$ we have*

$$\mathcal{SC}(M, N) = \mathcal{SC}\left(M, N, \frac{N(N + 1)}{2}\right).$$

3.3 Convex Polytopes Associated with m -Scalable Frames

The m -scalability of a frame $\Phi = \{\varphi_k\}_{k=1}^M$ is equivalent to the existence of nonnegative numbers $\{c_k\}_{k \in I}$ with $\#I = m \geq N$ such that

$$\Phi C^2 \Phi^T = A \text{Id}_N, \tag{2}$$

where $A > 0$ and C is the diagonal matrix with the weights c_k on its diagonal for $k \in I$ and 0 on for $k \notin I$. Note that this automatically implies $N \leq \#\{k \in I : c_k > 0\} \leq m \leq M$. Comparing corresponding entries from left- and right-hand side of (2), it is seen that for a frame to be m -scalable it is necessary and sufficient that there

exists a vector $u = (c_1^2, c_2^2, \dots, c_M^2)^T$ with $\|u\|_0 := \#\{k \in [M] : c_k \neq 0\} \leq m$ which is a solution of the following linear system of $\frac{N(N+1)}{2}$ equations in M unknowns:

$$\begin{cases} \sum_{j=1}^M \varphi_j(k)^2 y_j = A & \text{for } k = 1, \dots, N, \\ \sum_{j=1}^M \varphi_j(\ell) \varphi_j(k) y_j = 0 & \text{for } \ell, k = 1, \dots, N, k > \ell. \end{cases} \quad (3)$$

Subtraction of equations in the first system in (3) leads to the new *homogeneous* linear system

$$\begin{cases} \sum_{j=1}^M (\varphi_1(1)^2 - \varphi_j(k)^2) y_j = 0 & \text{for } k = 2, \dots, N, \\ \sum_{j=1}^M \varphi_j(\ell) \varphi_j(k) y_j = 0 & \text{for } \ell, k = 1, \dots, N, k > \ell. \end{cases} \quad (4)$$

It is not hard to see that we have not lost information in the last step, hence Φ is m -scalable if and only if there exists a nonnegative vector $u \in \mathbb{R}^M$ with $\|u\|_0 \leq m$ which is a solution to (4). In matrix form, (4) reads

$$F(\Phi)u = 0,$$

where the $(N-1)(N+2)/2 \times M$ matrix $F(\Phi)$ is given by

$$F(\Phi) = (F(\varphi_1) \quad F(\varphi_2) \quad \dots \quad F(\varphi_M)),$$

where $F : \mathbb{R}^N \rightarrow \mathbb{R}^d$, $d := (N-1)(N+2)/2$, is defined by

$$F(x) = \begin{pmatrix} F_0(x) \\ F_1(x) \\ \vdots \\ F_{N-1}(x) \end{pmatrix}, \quad F_0(x) = \begin{pmatrix} x_1^2 - x_2^2 \\ x_1^2 - x_3^2 \\ \vdots \\ x_1^2 - x_N^2 \end{pmatrix}, \quad F_k(x) = \begin{pmatrix} x_k x_{k+1} \\ x_k x_{k+2} \\ \vdots \\ x_k x_N \end{pmatrix},$$

and $F_0(x) \in \mathbb{R}^{N-1}$, $F_k(x) \in \mathbb{R}^{N-k}$, $k = 1, 2, \dots, N-1$. Summarizing, we have just proved the following proposition.

PROPOSITION 3.7. *A frame Φ for \mathbb{R}^N is (strictly) m -scalable if and only if there exists a nonnegative $u \in \ker F(\Phi) \setminus \{0\}$ with $\|u\|_0 \leq m$ (respectively, $\|u\|_0 = m$).*

We will now utilize the above reformulation to characterize m -scalable frames in terms of the properties of convex polytopes of the type $\text{co}(F(\Phi_I))$, $I \subset [M]$. One of the key tools will be the Farkas lemma (see, e.g., [20, Lemma 1.2.5]).

LEMMA 3.8. *For every real $N \times M$ -matrix A exactly one of the following cases occurs:*

- (i) *The system of linear equations $Ax = 0$ has a nontrivial nonnegative solution $x \in \mathbb{R}^M$ (all components of x are nonnegative and at least one of them is strictly positive.)*
- (ii) *There exists $y \in \mathbb{R}^N$ such that $y^T A$ is a vector with all entries strictly positive.*

THEOREM 3.9. *Let $M \geq N \geq 2$, and let m be such that $N \leq m \leq M$. Assume that $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}^*(M, N)$ is such that $\varphi_k \neq \varphi_\ell$ when $k \neq \ell$. Then the following statements are equivalent:*

- (i) *Φ is (strictly) m -scalable.*
- (ii) *There exists a subset $I \subset [M]$ with $\#I = m$ such that $0 \in \text{co}(F(\Phi_I))$ (respectively, $0 \in \text{ri co}(F(\Phi_I))$).*
- (iii) *There exists a subset $I \subset [M]$ with $\#I = m$ for which there is no $h \in \mathbb{R}^d$ with $\langle F(\varphi_k), h \rangle > 0$ for all $k \in I$ (respectively, with $\langle F(\varphi_k), h \rangle \geq 0$ for all $k \in I$, with at least one of the inequalities being strict).*

We now derive a few consequences of the above theorem. A given a vector $v \in \mathbb{R}^d$ defines a hyperplane by

$$H(v) = \{y \in \mathbb{R}^d : \langle v, y \rangle = 0\},$$

which itself determines two open convex cones $H^-(v)$ and $H^+(v)$, defined by

$$H^-(v) = \{y \in \mathbb{R}^d : \langle v, y \rangle < 0\} \quad \text{and} \quad H^+(v) = \{y \in \mathbb{R}^d : \langle v, y \rangle > 0\}.$$

Using these notations we can restate the equivalence (i) \Leftrightarrow (iii) in Theorem 3.9 as follows:

PROPOSITION 3.10. *Let $M \geq N \geq 2$, and let m be such that $N \leq m \leq M$. Assume that $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}^*$ is such that $\varphi_k \neq \varphi_\ell$ when $k \neq \ell$. Φ is m -scalable if and only if there exists a subset $I \subset [M]$ with $\#I = m$ such that $\bigcap_{i \in I} H^+(F(\varphi_i)) = \emptyset$.*

The following result is an application of Proposition 3.10 which provides an easy condition for $\Phi \notin \mathcal{SC}(M, N)$. It relies on the fact that $\Phi \in \mathcal{SC}(M, N)$ if and only if $T(\Phi) \in \mathcal{SC}(M, N)$ for all orthogonal transformations T on \mathbb{R}^N , [17, Corollary 2.6].

PROPOSITION 3.11. *Let $\Phi = \{\varphi_k\}_{k=1}^M$ be a frame for \mathbb{R}^N , $N \geq 2$. If there exists an isometry T such that $T(\Phi) \subset \mathbb{R}^{N-2} \times \mathbb{R}_+^2$, then Φ is not scalable.*

The characterizations stated above can be recast in terms of the convex cone $C(F(\Phi))$ generated by $F(\Phi)$. We state this result for the sake of completeness. But first, recall that for a finite subset $X = \{x_1, \dots, x_M\}$ of \mathbb{R}^d the *polyhedral cone generated by X* is the closed convex cone set $C(X)$ defined by

$$C(X) = \left\{ \sum_{i=1}^M \alpha_i x_i : \alpha_i \geq 0 \right\}.$$

Let C be a cone in \mathbb{R}^d . The *polar cone* of C is the closed convex cone C° defined by

$$C^\circ := \{x \in \mathbb{R}^N : \langle x, y \rangle \leq 0 \text{ for all } y \in C\}.$$

The cone C is said to be *pointed* if $C \cap (-C) = \{0\}$, and *blunt* if the linear space generated by C is \mathbb{R}^N , i.e. $\text{span } C = \mathbb{R}^N$.

COROLLARY 3.12. *Let $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}^*$, and let $N \leq m \leq M$ be fixed. Then the following conditions are equivalent:*

- (i) Φ is strictly m -scalable .
- (ii) There exists $I \subset [M]$ with $\#I = m$ such that $C(F(\Phi_I))$ is not pointed.
- (iii) There exists $I \subset [M]$ with $\#I = m$ such that $C(F(\Phi_I))^\circ$ is not blunt.
- (iv) There exists $I \subset [M]$ with $\#I = m$ such that the interior of $C(F(\Phi_I))^\circ$ is empty.

4. TOPOLOGY OF THE SET OF SCALABLE FRAMES

In this section, we present some topological features of the set $\mathcal{SC}(M, N)$. Hereby, we identify frames in $\mathcal{F}(M, N)$ with real $N \times M$ matrices as we already did before, see, e.g., (2) in subsection 3.3. Hence, we consider $\mathcal{F}(M, N)$ as the set of all matrices in $\mathbb{R}^{N \times M}$ of rank N . Note that under this identification the order of the vectors in a frame becomes important.

In [17] it was proved that $\mathcal{SC}(M, N)$ is a closed set in $\mathcal{F}(M, N)$ (in the relative topology of $\mathcal{F}(M, N)$). The next proposition refines this fact.

PROPOSITION 4.1. *If $N \leq m \leq M$, then $\mathcal{SC}(M, N, m)$ is closed in $\mathcal{F}(M, N)$.*

The next theorem is the main result of this section. It shows that the set of scalable frames is nowhere dense in the set of frames if only M is not “too large” with respect to N .

THEOREM 4.2. *Let $M \geq N \geq 2$. If $M < d + 1 = N(N + 1)/2$ then $\mathcal{SC}(M, N)$ does not contain interior points. In other words, for the boundary of $\mathcal{SC}(M, N)$ we have*

$$\partial\mathcal{SC}(M, N) = \mathcal{SC}(M, N).$$

The proof of Theorem 4.2 given in [19], is based on the following two lemmas. Recall that for a frame $\Phi = \{\varphi_k\}_{k=1}^M \in \mathcal{F}$ we use the notation

$$X_\Phi = \{\varphi_i \varphi_i^T : i \in [M]\}.$$

LEMMA 4.3. *Let $\{\varphi_k\}_{k=1}^M \subset \mathbb{R}^N$ be such that $\dim \text{span } X_\Phi < \frac{N(N+1)}{2}$. Then there exists $\varphi_0 \in \mathbb{R}^N$ with $\|\varphi_0\| = 1$ such that $\varphi_0 \varphi_0^T \notin \text{span } X_\Phi$.*

The following lemma shows that for a generic M -element set $\{\varphi_i\}_{i=1}^M \subset \mathbb{R}^N$ (or matrix in $\mathbb{R}^{N \times M}$, if the φ_i are considered as columns) the subspace $\text{span } X_\Phi$ has the largest possible dimension.

LEMMA 4.4. *Let $D := \min\{M, N(N + 1)/2\}$. Then the set*

$$\{\Phi \in \mathbb{R}^{N \times M} : \dim \text{span } X_\Phi = D\}$$

is dense in $\mathbb{R}^{N \times M}$.

REMARK 4.5. *For the case $M \geq N(N + 1)/2$, Lemma 4.4 has been proved in [4, Theorem 2.1]. In the proof, the authors note that X_Φ spans S_N if and only if the frame operator of X_Φ (considered as a system in S_N) is invertible. But the determinant of this operator is a polynomial in the entries of φ_i , and the complement of the set of roots of such polynomials is known to be dense.*

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