



Summer School on Numerical Linear Algebra for Dynamical and  
High-Dimensional Problems

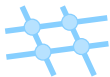
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# Solution of Computational Problems for Descriptor Systems

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NETWORK THEORY



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# Descriptor Systems

Given: LTI descriptor system

$$\Sigma : \begin{cases} E\dot{x}(t) = Ax(t) + Bu(t), \\ y(t) = Cx(t) + Du(t), \end{cases}$$

- $E, A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{n \times m}$ ,  $C \in \mathbb{R}^{p \times n}$ ,  $D \in \mathbb{R}^{p \times m}$ ,
- descriptor vector  $x(t) \in \mathbb{R}^n$ , input vector  $u(t) \in \mathbb{R}^m$ , output vector  $y(t) \in \mathbb{R}^p$ .
- **Assumptions:**  $\lambda E - A$  is **regular**, i.e.  $\det(\lambda E - A) \neq 0$ .

Transfer function

$$G(s) = C(sE - A)^{-1}B + D$$

# Additional Structures

## Bounded realness

- $G$  has no poles with nonnegative real parts,
- $I - G(i\omega)G^H(i\omega) \succcurlyeq 0$  for all values  $\omega \in \mathbb{R}$ .

## Positive realness

- $G$  has no poles with positive real parts,
- $G(i\omega) + G^H(i\omega) \succcurlyeq 0$  for any  $i\omega$  that is not a pole of  $G$  with  $\omega \in \mathbb{R}$ ,
- if  $i\omega$  or  $\infty$  is a pole of  $G$ , then it is simple and the relevant residue matrix is positive semidefinite Hermitian.

## General frequency domain inequalities (FDIs)

$$\begin{bmatrix} (i\omega E - A)^{-1}B \\ I \end{bmatrix}^H \begin{bmatrix} Q & S \\ S^T & R \end{bmatrix} \begin{bmatrix} (i\omega E - A)^{-1}B \\ I \end{bmatrix} \succcurlyeq 0, \quad Q = Q^T, \quad R = R^T.$$

# Connection to Linear Matrix Inequalities

## Bounded real lemma

Under certain conditions:  $G$  is bounded real if and only if the LMI

$$\begin{bmatrix} A^T X + X^T A + C^T C & X^T B + C^T D \\ B^T X + D^T C & D^T D - I \end{bmatrix} \preceq 0, \quad E^T X = X^T E \succcurlyeq 0 \text{ is feasible.}$$

## Positive real lemma

Under certain conditions:  $G$  is positive real if and only if the LMI

$$\begin{bmatrix} A^T X + X^T A & X^T B - C^T \\ B^T X - C & -D^T - D \end{bmatrix} \preceq 0, \quad E^T X = X^T E \succcurlyeq 0 \text{ is feasible.}$$

## Kalman-Yakubovič-Popov lemma

Under certain conditions: FDI holds for all  $i\omega$  if and only if the LMI

$$\begin{bmatrix} A^T X + X^T A + Q & X^T B + S \\ B^T X + S^T & R \end{bmatrix} \succcurlyeq 0, \quad E^T X = X^T E \text{ is feasible.}$$

# Problems under Consideration

## Weakening equivalence conditions

The conditions which are needed to state equivalence are quite strong at the moment  $\implies$  weakening these conditions to make it more practical.

## Passivity enforcement

Bounded realness/positive realness/FDI are natural properties of real-world systems. Often these are lost due to modeling errors/approximation errors  $\implies$  restore this by introducing small errors to system's matrices (can be done by perturbation of purely imaginary eigenvalues of skew-Hamiltonian/Hamiltonian matrix pencils (next slide)).

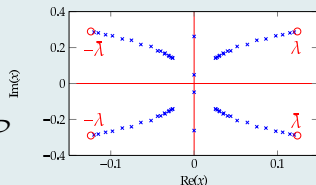
# Skew-Hamiltonian/Hamiltonian Matrix Pencils

## Properties

- block structure:  $\lambda \mathcal{S} - \mathcal{H} = \lambda \begin{bmatrix} F & G \\ H & F^T \end{bmatrix} - \begin{bmatrix} R & S \\ T & -R^T \end{bmatrix}$  with skew-Hermitian  $G$ ,  $H$ , and Hermitian  $S$ ,  $T$ ,
- Hamiltonian eigensymmetry (symmetry with respect to imaginary axis (and the real axis in the real case)),
- pencils  $\lambda \tilde{\mathcal{S}} - \tilde{\mathcal{H}} := \mathcal{J} \mathcal{P}^T \mathcal{J}^T (\lambda \mathcal{S} - \mathcal{H}) \mathcal{P}$  with  $\mathcal{J} = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix}$  are again sH/H,
- structured Schur form:

$$\mathcal{J} \mathcal{Q}^T \mathcal{J}^T (\lambda \mathcal{S} - \mathcal{H}) \mathcal{Q} = \lambda \begin{bmatrix} S_1 & S_2 \\ 0 & S_1^T \end{bmatrix} - \begin{bmatrix} H_1 & H_2 \\ 0 & -H_1^T \end{bmatrix},$$

with orthogonal  $\mathcal{Q}$ , upper triangular  $S_1$ , and  $H_1$ ; however **existence cannot be guaranteed**, can be solved by structured embedding.



# Problems under Consideration

## Structure-preserving balancing

Goal: find a **simple**  $\mathcal{J}$ -congruence transform such that:

- in the transformed pencil a maximum number of eigenvalues has been isolated (i.e., part of the pencil is in structured Schur form),
- in the remainder, the rows and columns of the pencil are as close in norm as possible (to improve numerical accuracy).

## Perturbation theory for purely imaginary eigenvalues

For many applications the interesting eigenvalues of skew-Hamiltonian/Hamiltonian pencils are the purely imaginary ones.

**Question:** How to move these eigenvalues off the imaginary axis by **structured perturbations**?

- **might** be possible by arbitrarily small perturbations if some of the purely imaginary eigenvalues are not simple,
- depends on the skew-Hamiltonian/Hamiltonian Kronecker canonical form.